

# Mars Relay Operations

The Technical Challenges of  
Operating a Network at Mars

Greg J. Kazz

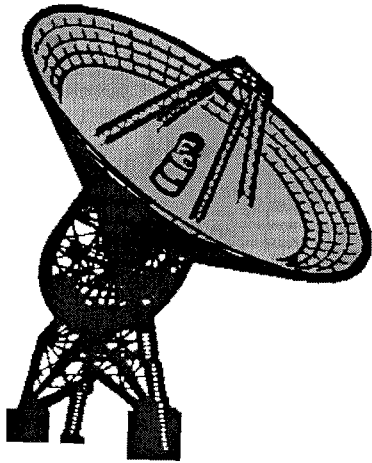
NASA/JPL

19 April 2002

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**What is the Deep Space Network?**

**How did it get this way?**

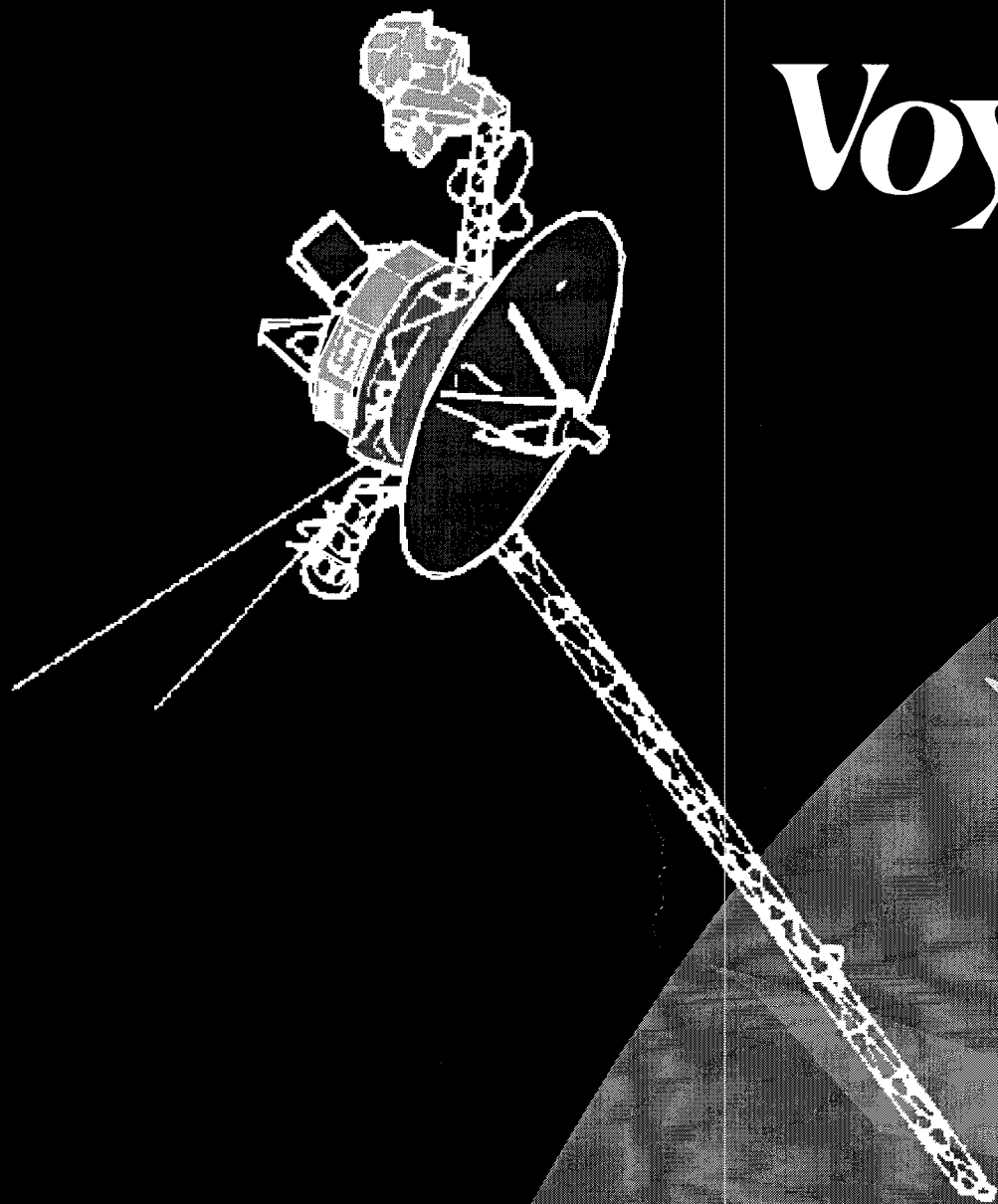


**Where are we going?**

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# *Voyager*

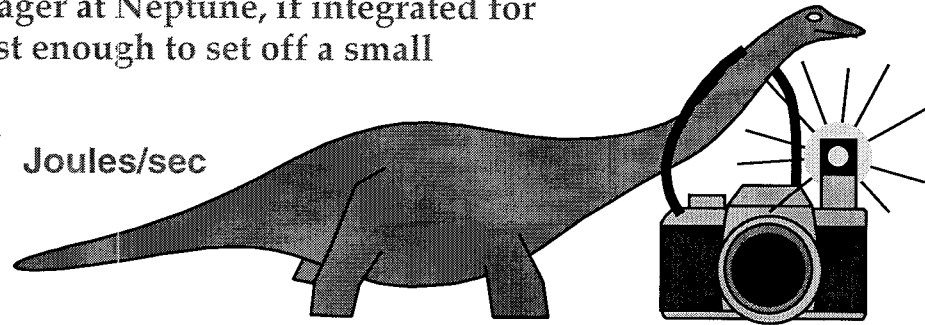


# CHARACTERISTICS OF DEEP SPACE MISSIONS

## Received Signal Sensitivity:

The received energy from Voyager at Neptune, if integrated for 300 million years, would be just enough to set off a small photographic flashbulb!

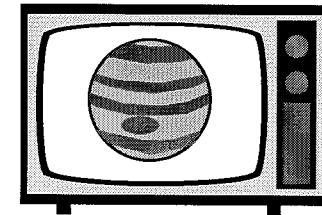
Received power =  $10^{-16}$  Joules/sec



## Command Power:

The DSN puts out enough power in commanding Voyager that it could easily provide high quality commercial TV at Jupiter!

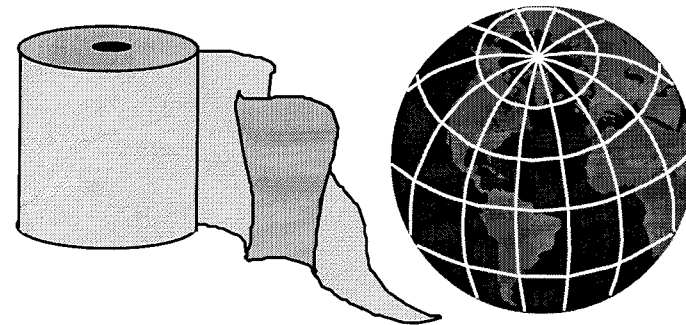
Transmitted power = 400 KW



## Dynamic Range of the DSN:

The ratio of the received signal power to the DSN transmitting power is like comparing the thickness of a sheet of toilet paper to the entire Earth!

Ratio =  $10^{21}$

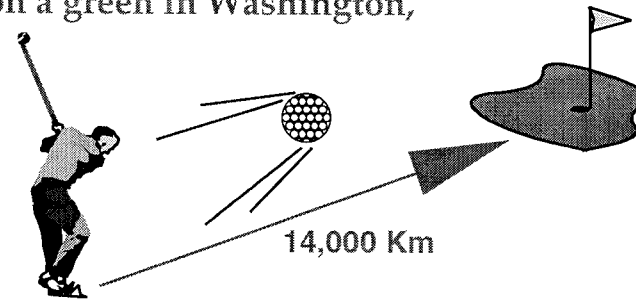


# CHARACTERISTICS OF DEEP SPACE MISSIONS

## Navigational Accuracy:

Voyager navigation at Neptune is equivalent to being able to tee – off from California and place the ball on a green in Washington, D.C.!

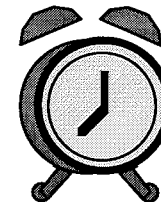
Angular accuracy = 50 nrad



## Frequency Stability:

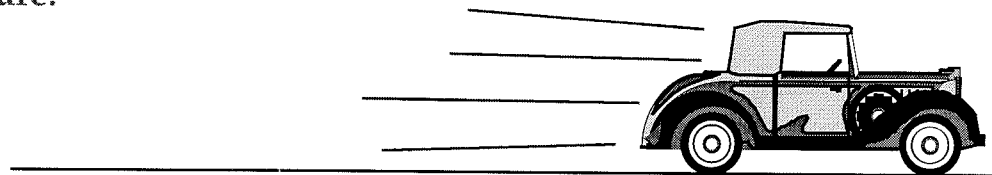
The DSN's atomic clocks used to achieve this navigation accuracy are so stable that only one second of error would accumulate every 3 million years!

Allan variance =  $10^{-12}$  in 1000 seconds

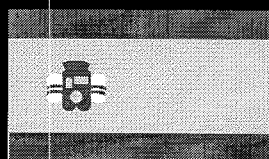
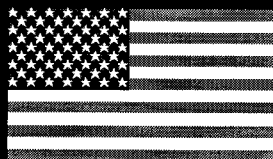
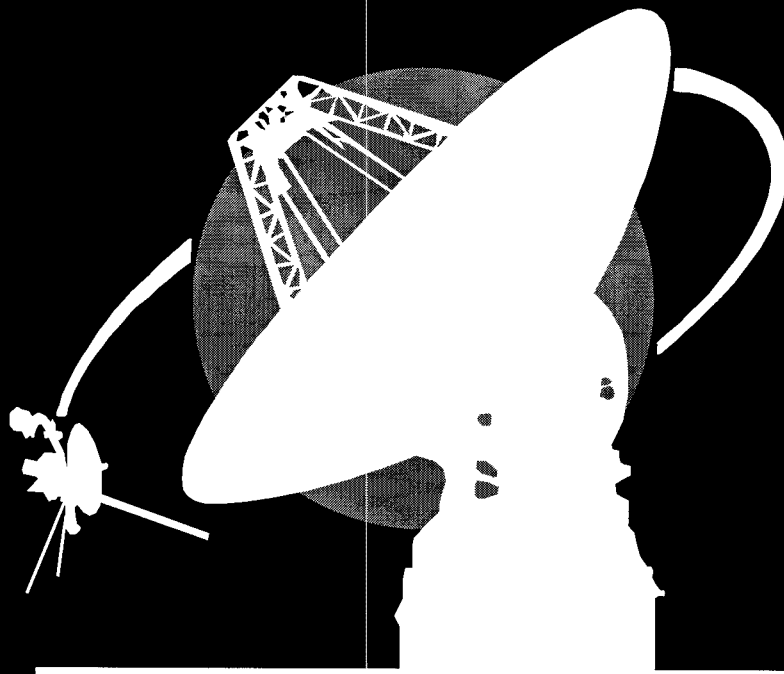


## Once-in-a-lifetime Science Opportunities:

The data from a Voyager planetary encounter is more valuable than the most rare Earth elements! The reliability of the spacecraft and the DSN together is equivalent to driving an automobile for 3 billion miles without a single failure!



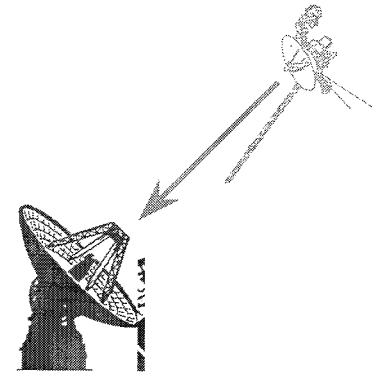
# DEEP SPACE NETWORK



# THE THREE MAJOR FUNCTIONS OF THE DSN:

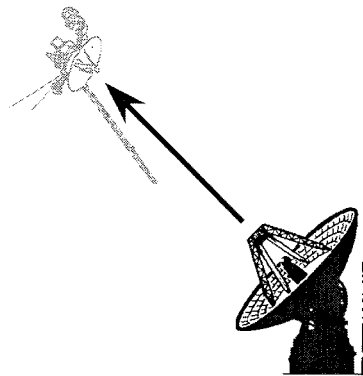
## TELEMETRY

Receiving data from the spacecraft



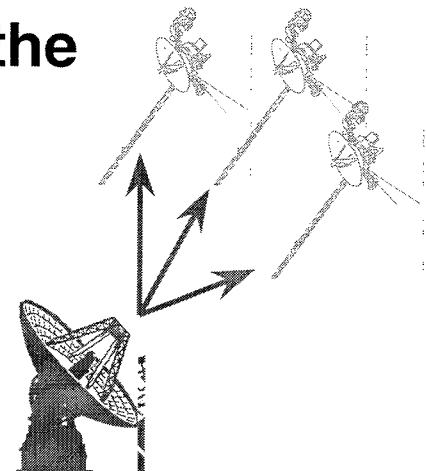
## COMMAND

Sending data to the spacecraft



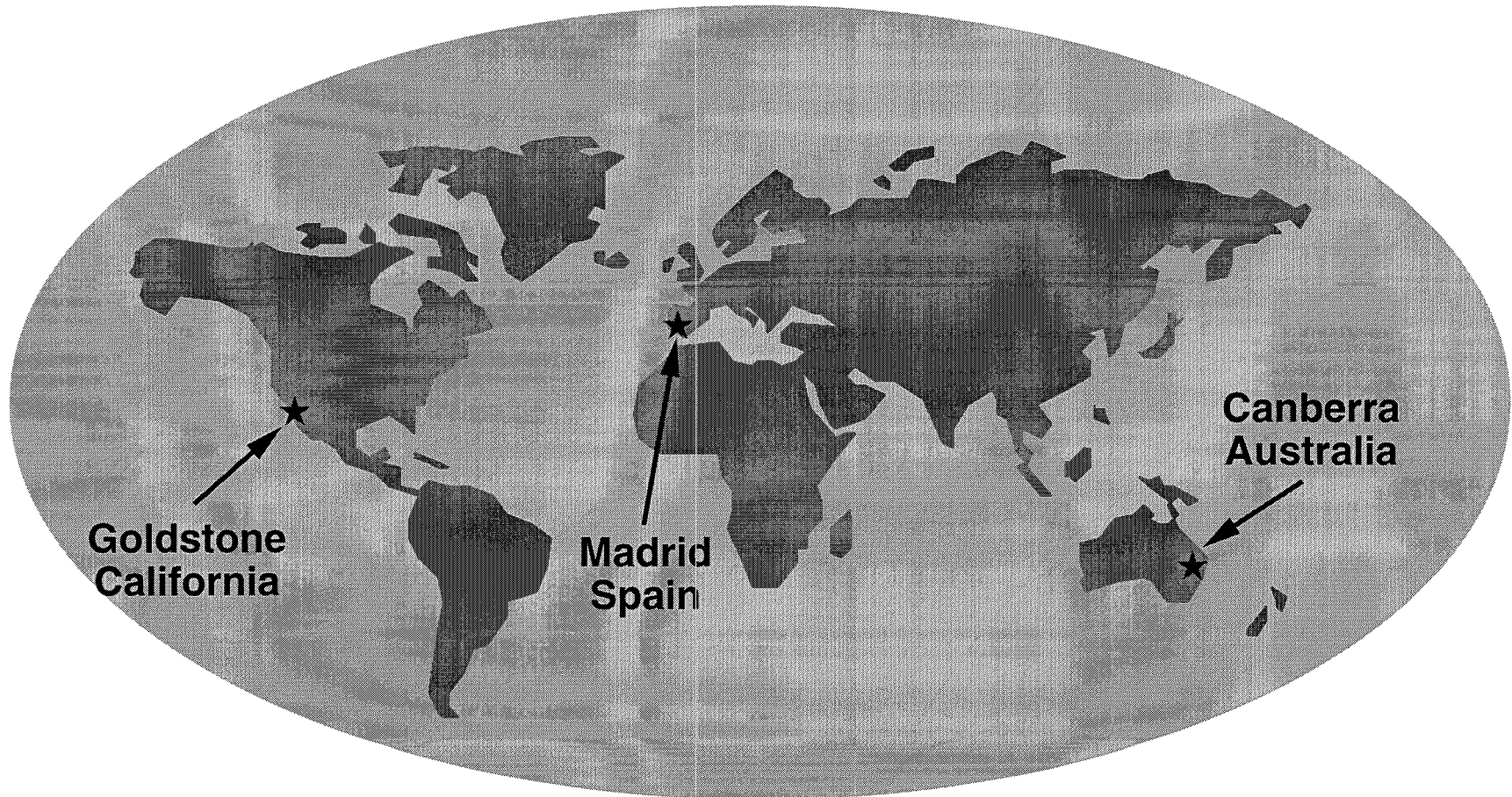
## NAVIGATION

Determining the spacecraft's position and velocity



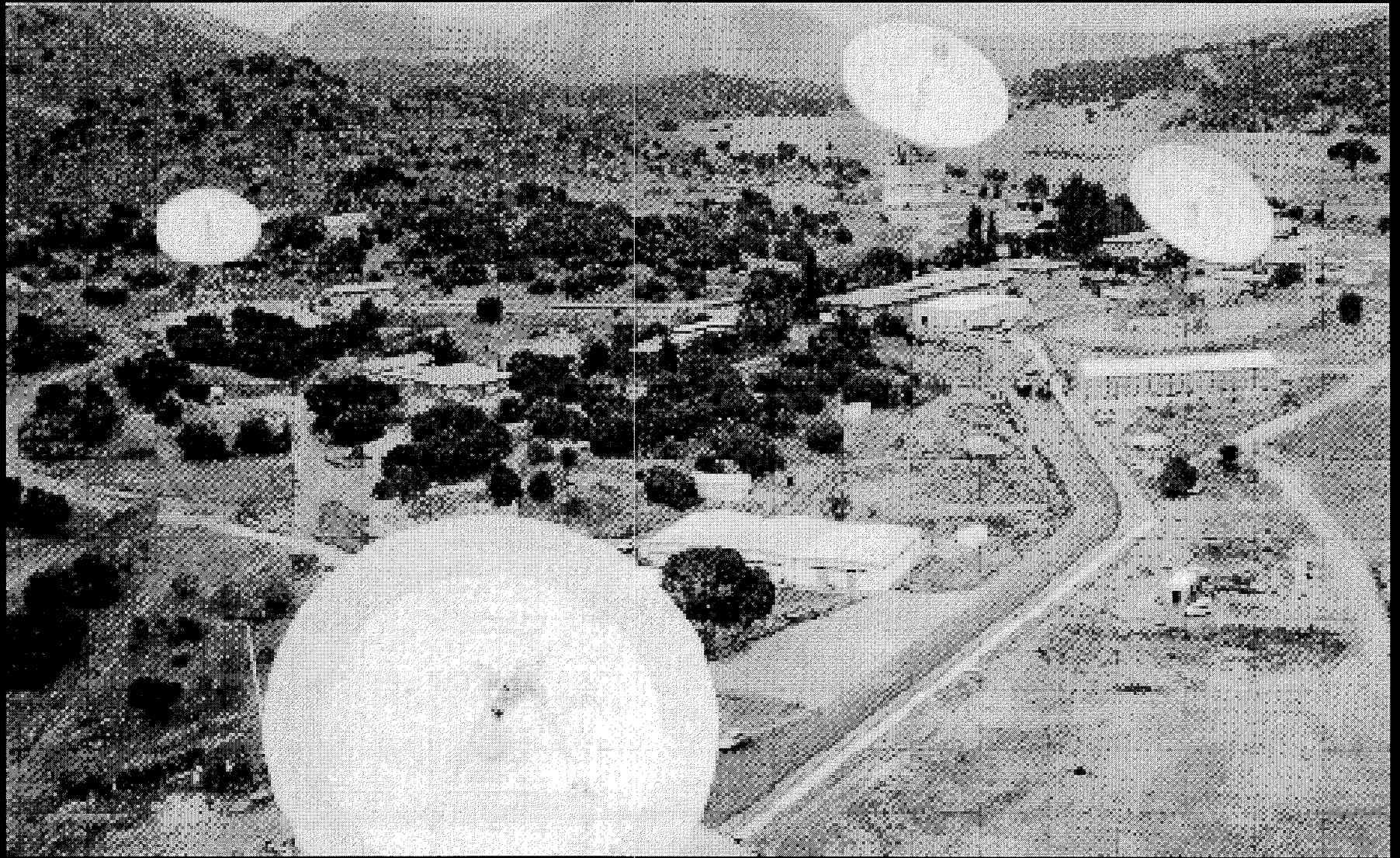
# DSN FACILITIES

The DSN operates three deep-space communications complexes that near continuous coverage of deep space missions is achieved



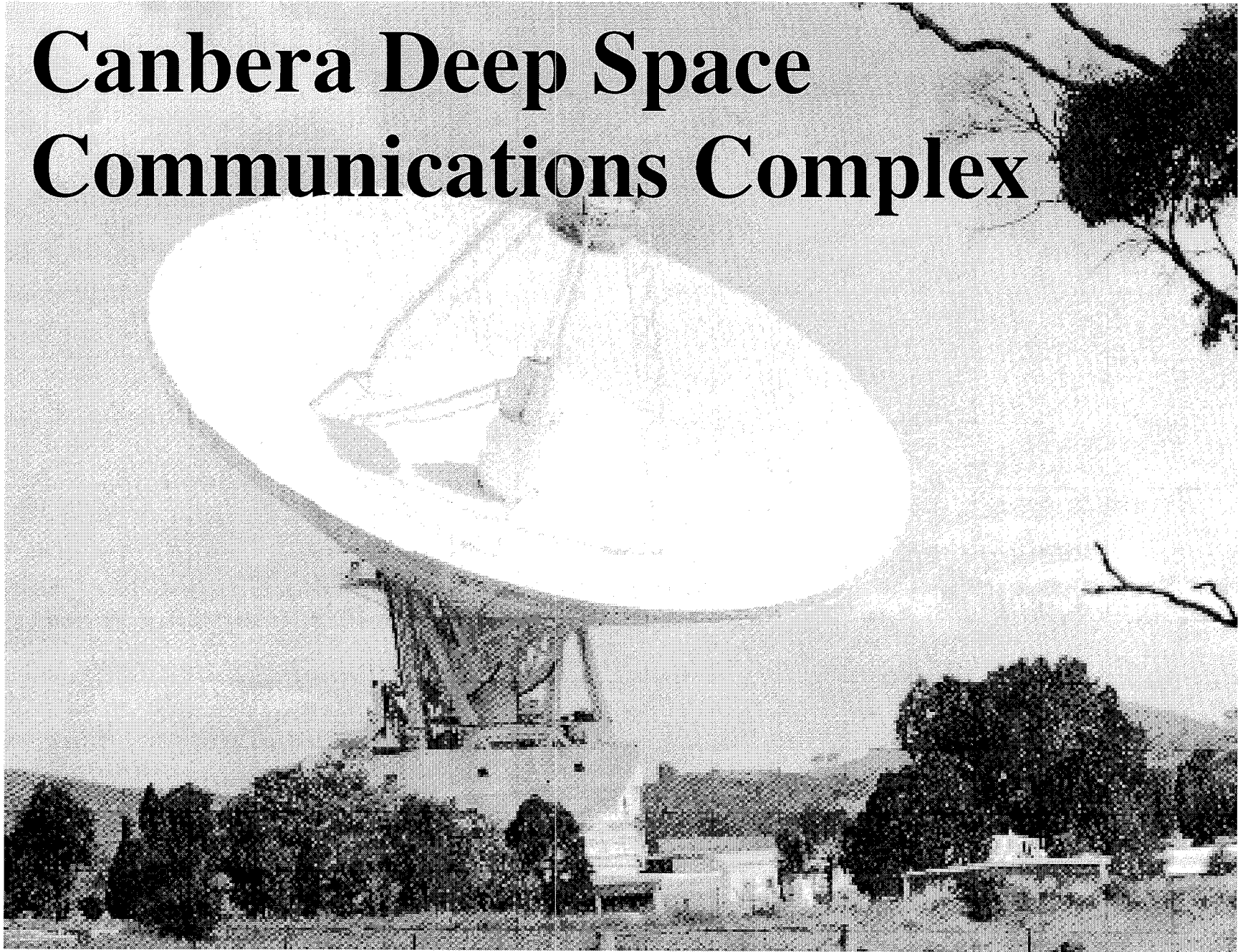
The DSN also operates facilities at JPL  
and at Cape Canaveral





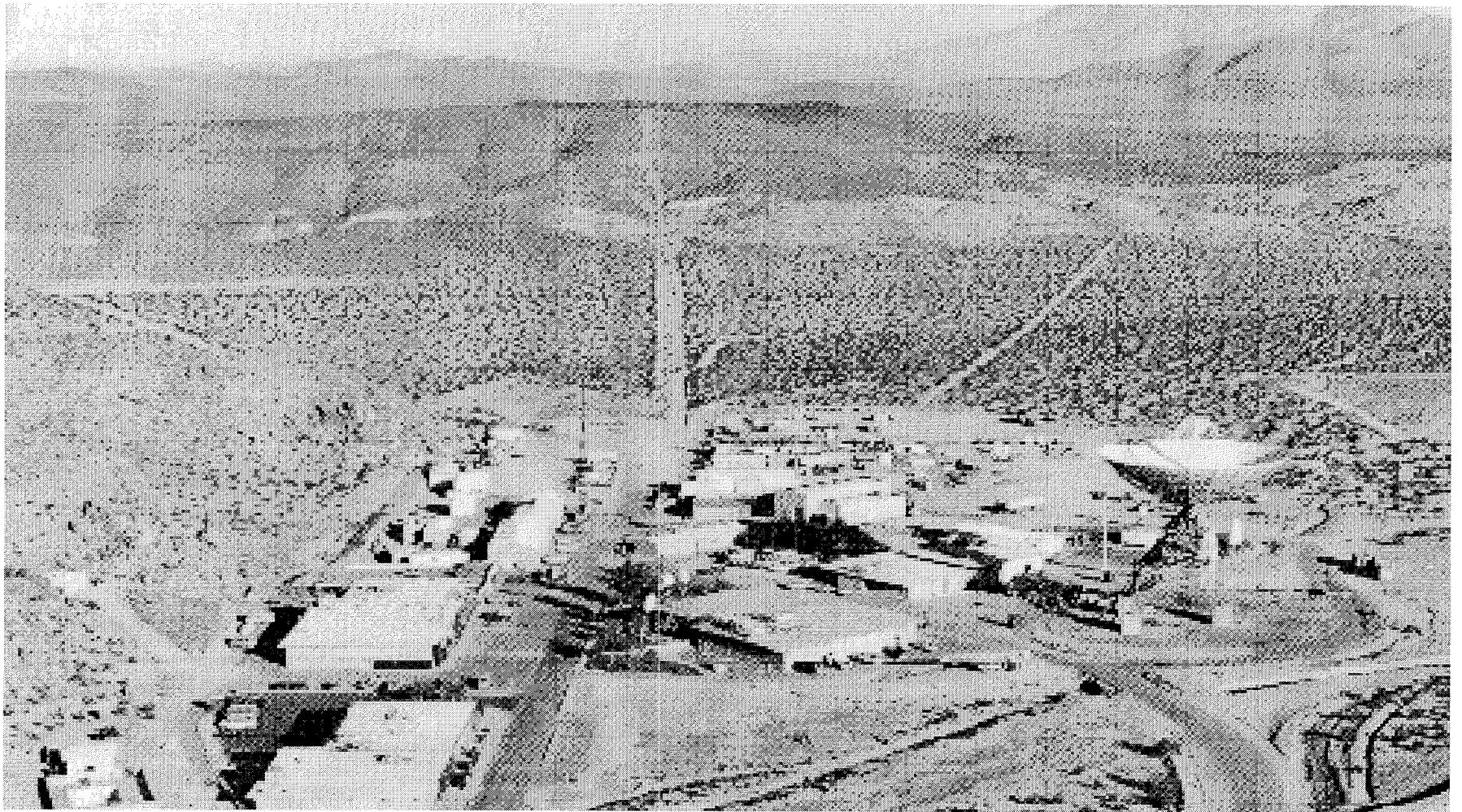
# **Madrid Deep Space Communications Complex**

# Canberra Deep Space Communications Complex

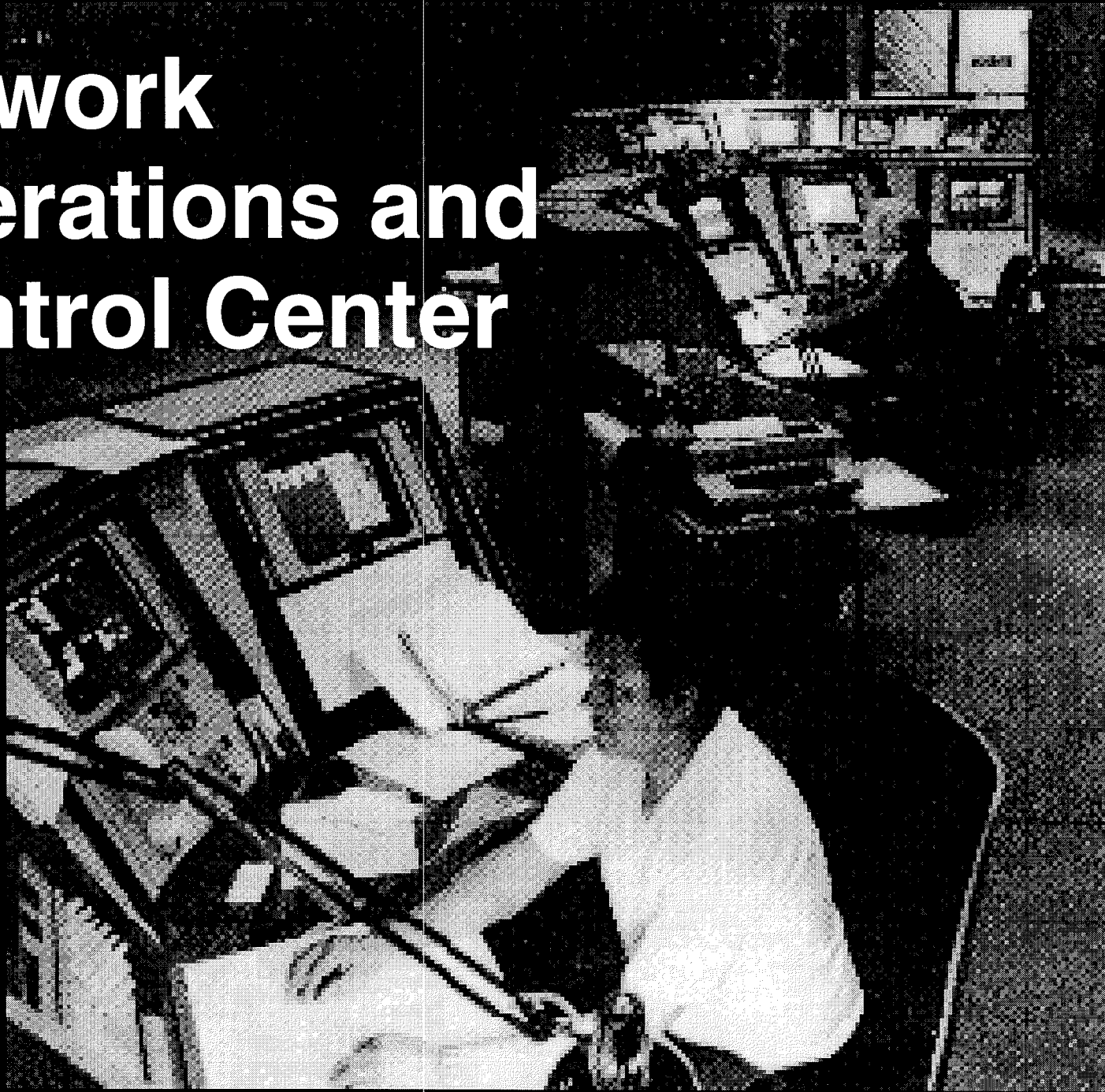




# Goldstone Deep Space Communications Complex



# Network Operations and Control Center

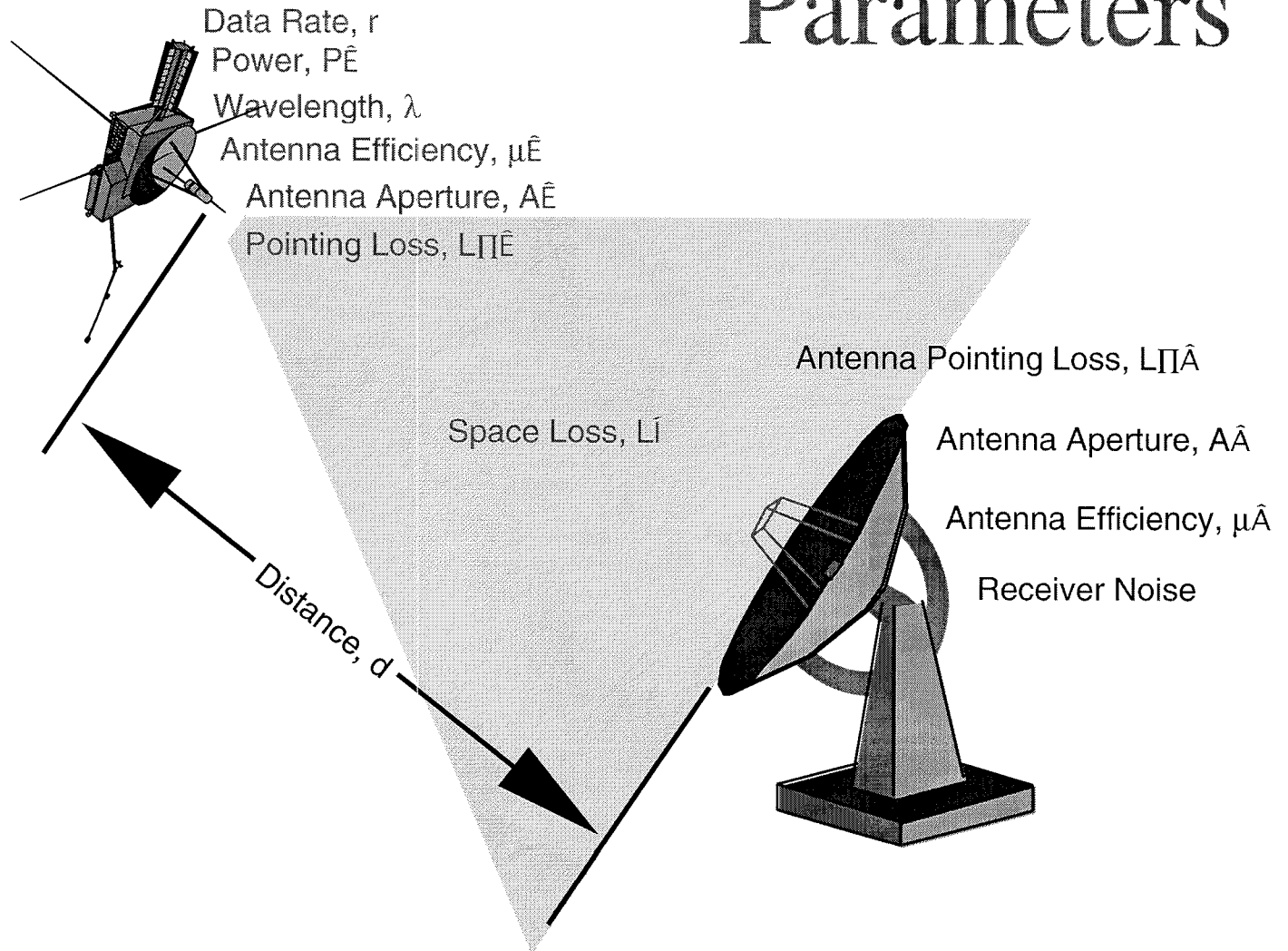


Hot Body Noise



Cosmic  
Background  
Noise

# Deep Space Link Parameters



# Deep Space Link Equations

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Space Loss

$$L_s = \left( \frac{\lambda}{4\pi d} \right)^2$$

Noise Spectral Density

$$N_0 = kT$$

Antenna Gain

$$G_A = \frac{4\pi A_e}{\lambda^2}$$

Noise Sources

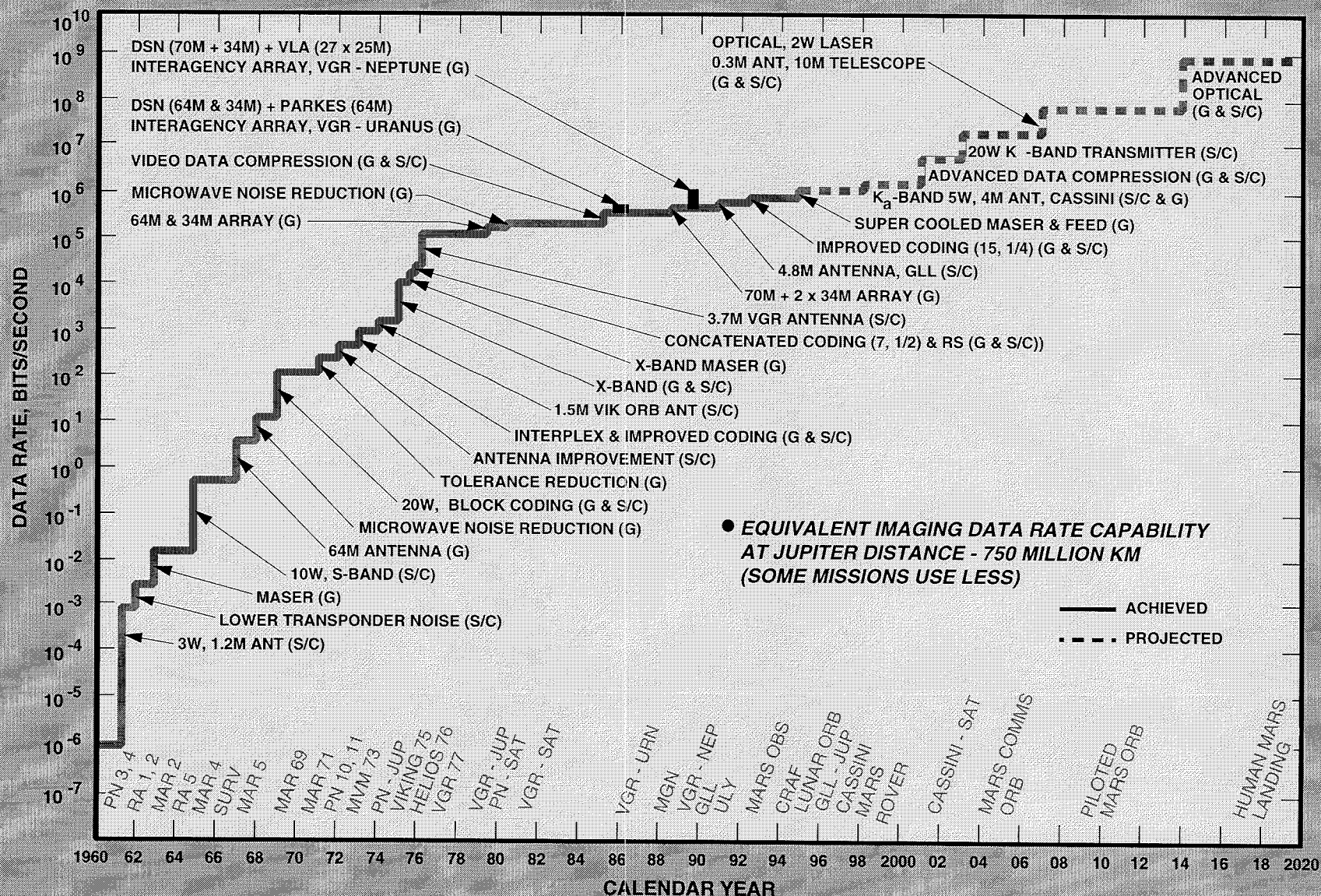
$$T = T_{\text{cosmic background}} \\ + T_{\text{hot bodies}} \\ + T_{\text{RFI}} \\ + T_{\text{atmosphere}} \\ + T_{\text{receiver}}$$

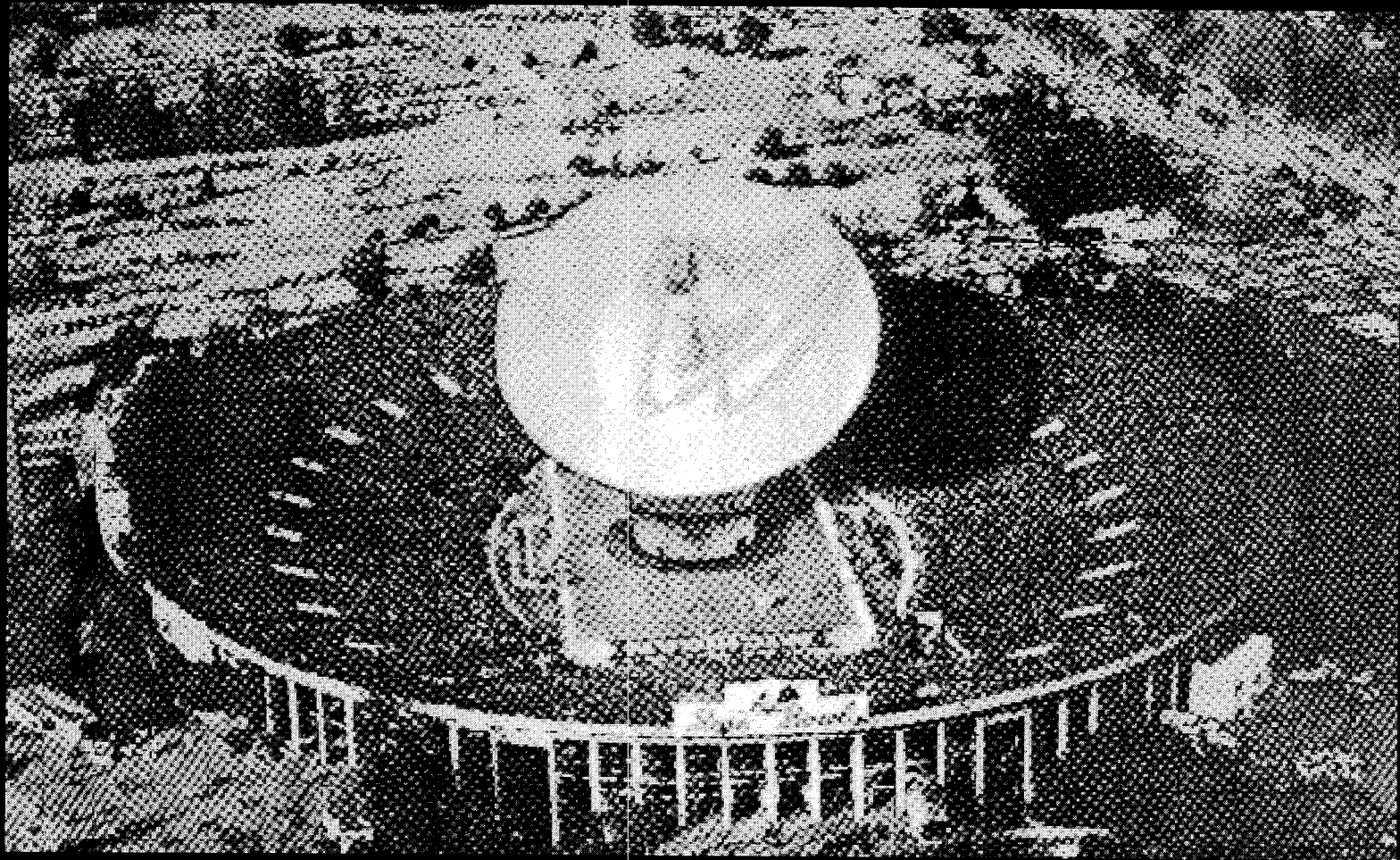
Received Power Per Bit

$$P_R = P_T G_T L_s G_R / r$$



# HISTORY OF TELEMETRY PERFORMANCE





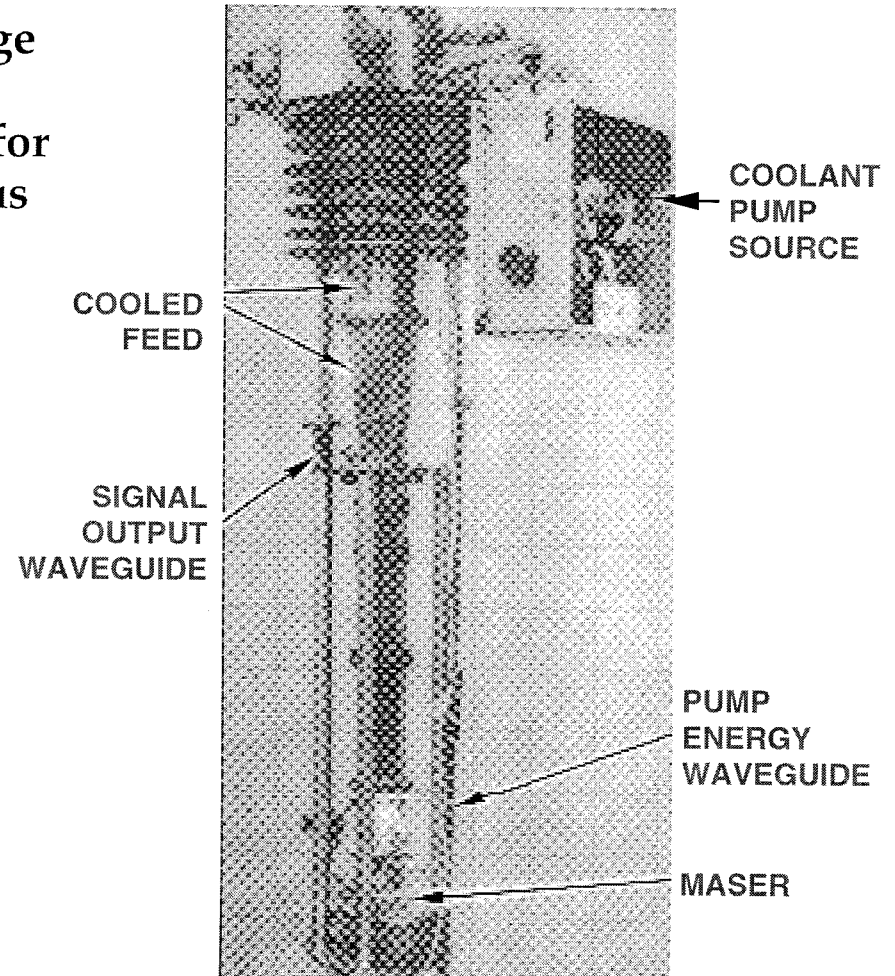
**70 METER ANTENNA IN  
THE ROSEBOWL**

# LOW NOISE AMPLIFIERS AND FEEDS

Many radio observatories have large antennas - only the DSN uses the lowest noise feeds and amplifiers for collecting the signals from the focus of the dish

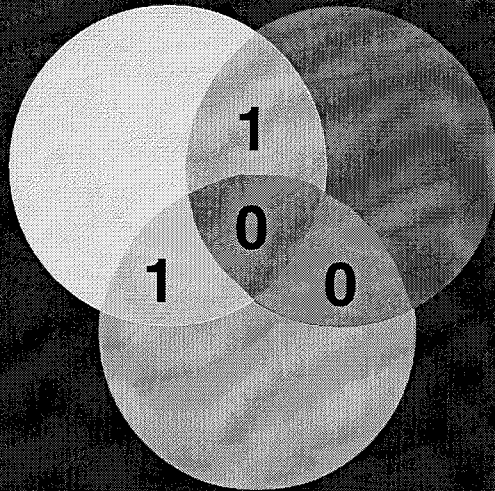
The DSN routinely uses maser amplifiers cooled to 4 degrees Kelvin

The latest technology in the DSN makes use of cooled feeds as well - and uses masers cooled to 1.9 k!

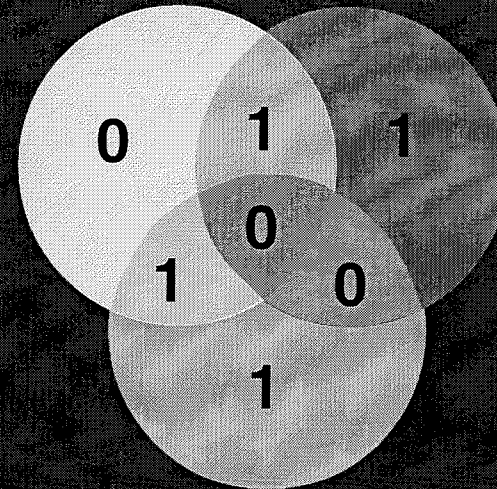




# An example of coding: the (7, 4) Hamming code

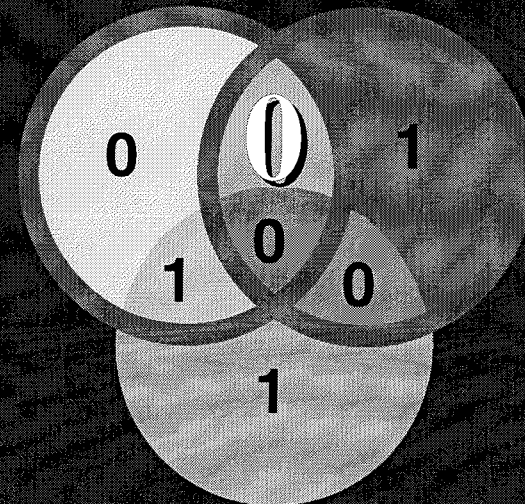
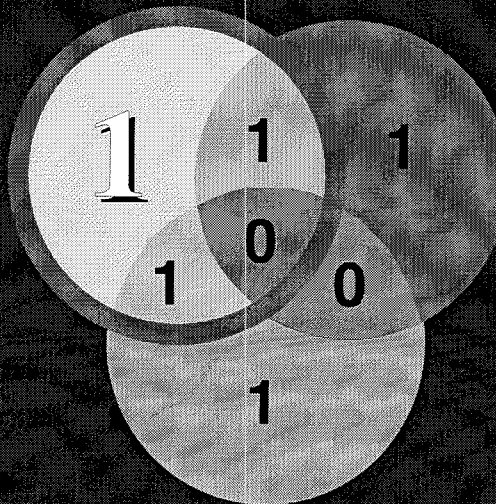


Place 4 information bits in the intersections of the Venn diagram



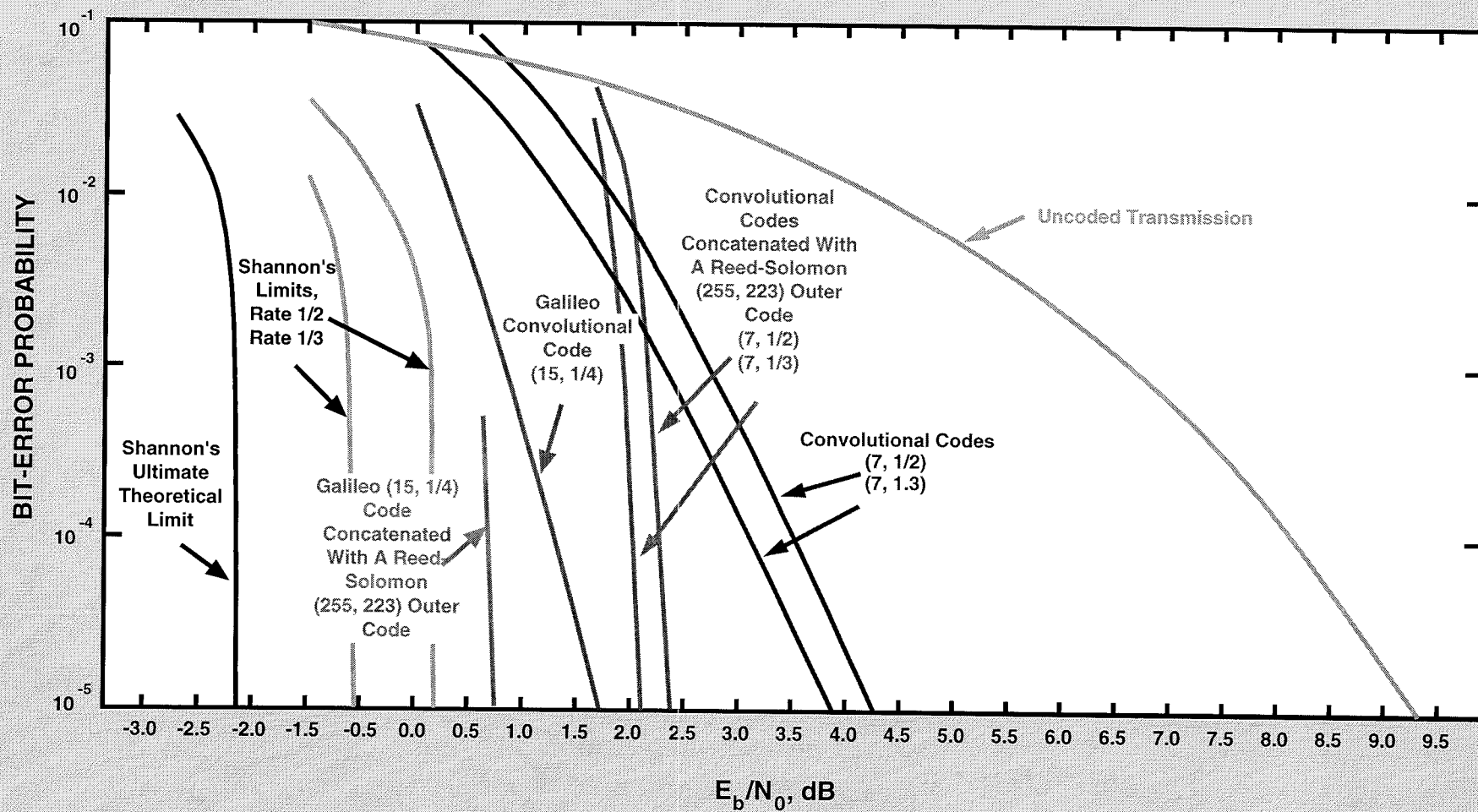
Fill in the rest of the diagram so that the large circles have an even number of 1's

If a single error occurs, it can be corrected by locating the circles with an odd number of 1's and changing the bit in their intersection

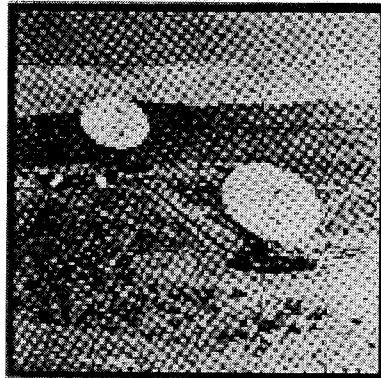




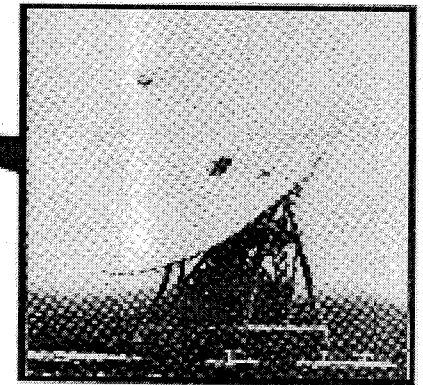
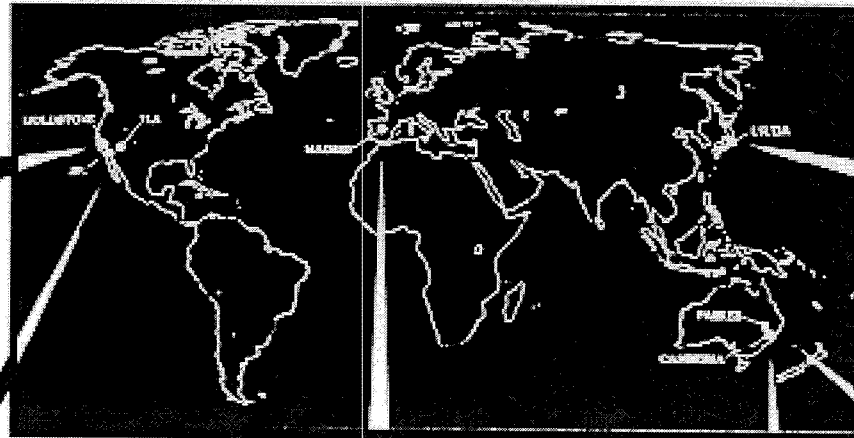
# Comparison of Several Coding Schemes



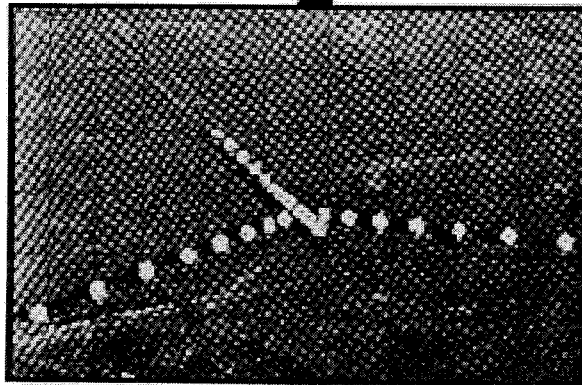
# *Voyager International Tracking Network*



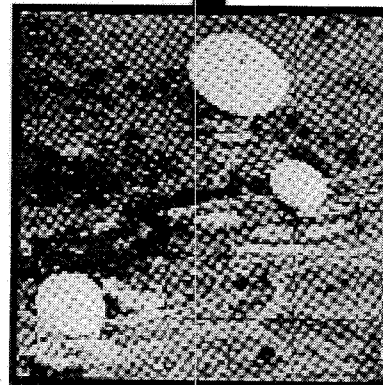
GOLDSTONE, CALIFORNIA



USUDA, JAPAN



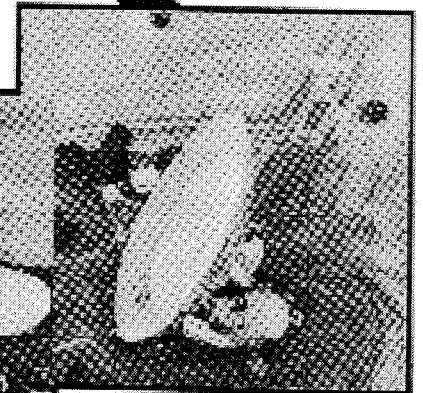
SOCORRO, NEW MEXICO



MADRID, SPAIN

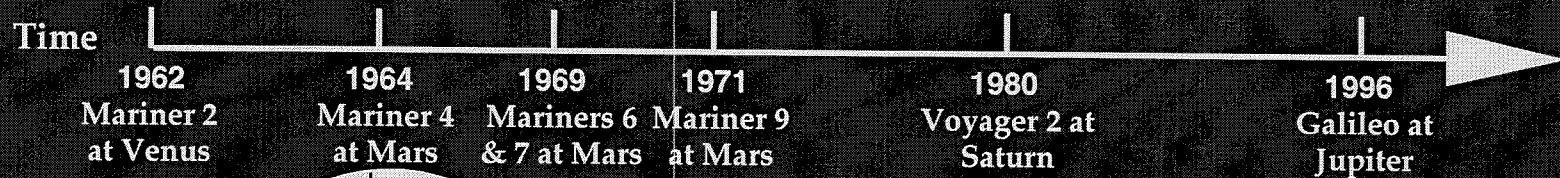


CANBERRA, AUSTRALIA



PARKES, AUSTRALIA

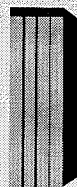
# History of Navigational Capability



Mountain  
1230 M



100 Story  
Building  
313 m



30 Story  
Building  
98 m



Small House  
3.7 m

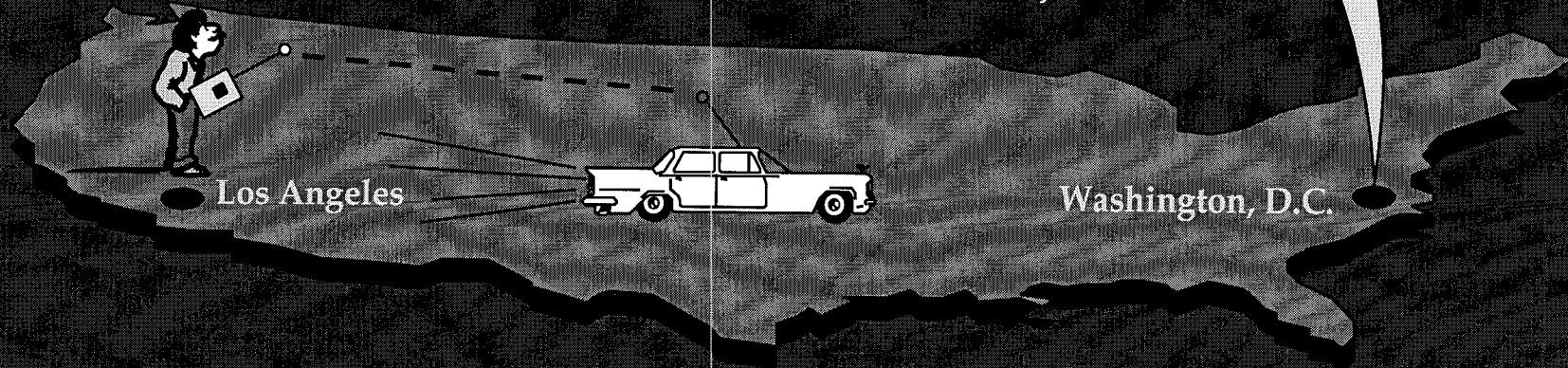


Office Chair  
61 cm



Computer Chip  
2.5 cm

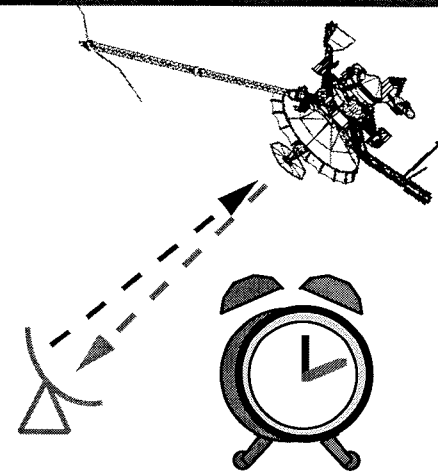
Equivalent to guiding a car on a journey from LA to DC while standing in LA and getting there to within the height of one of these common objects



# The Two Main Navigation Data Types Used by the DSN

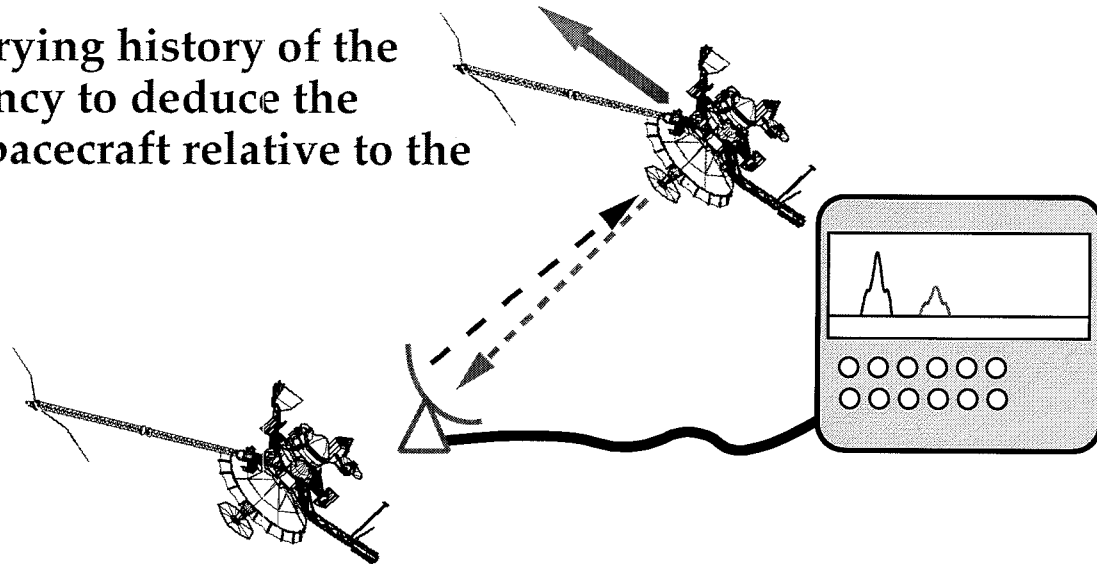
## RANGING:

Use the length of time for the signal to propagate from the DSN to the spacecraft and back to deduce the distance to the spacecraft



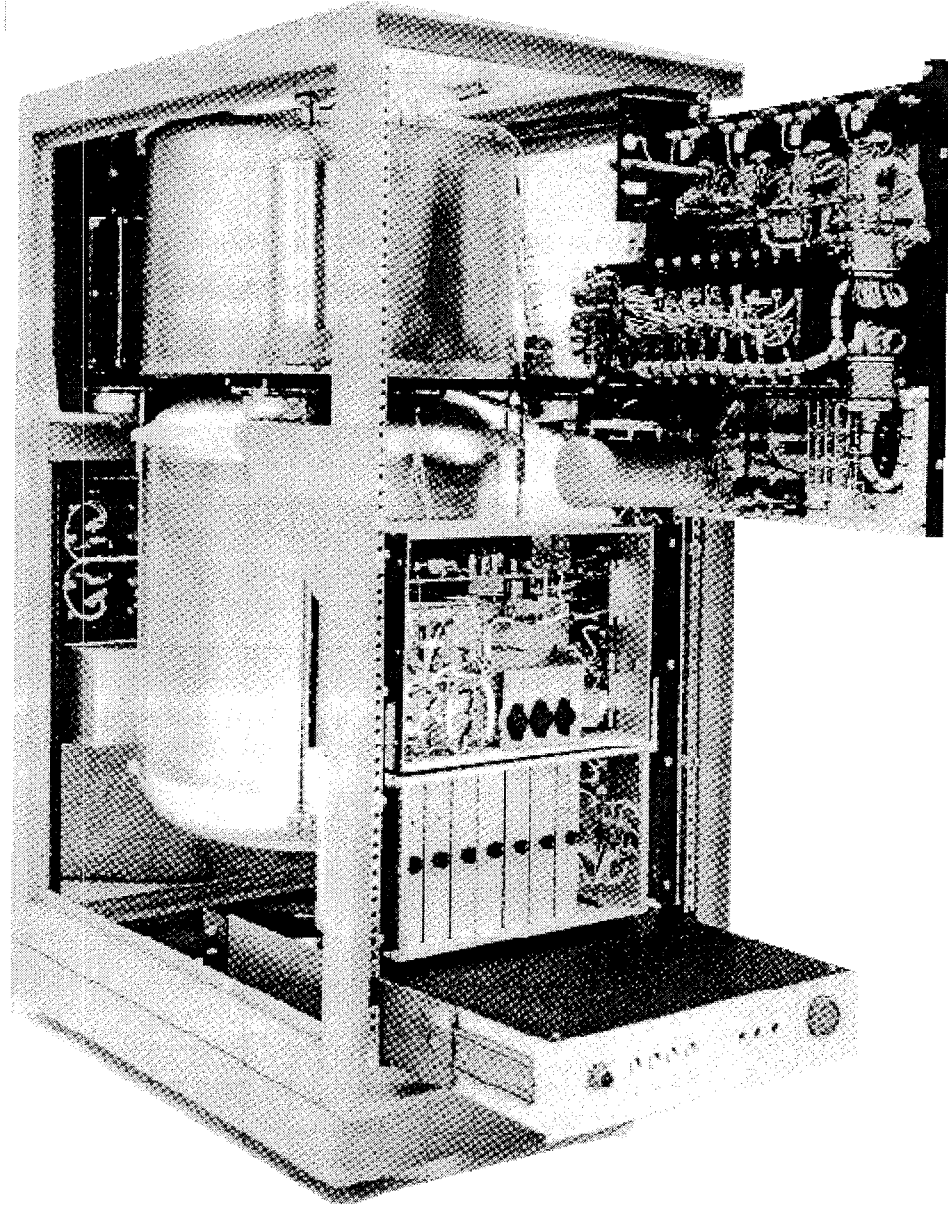
## DOPPLER:

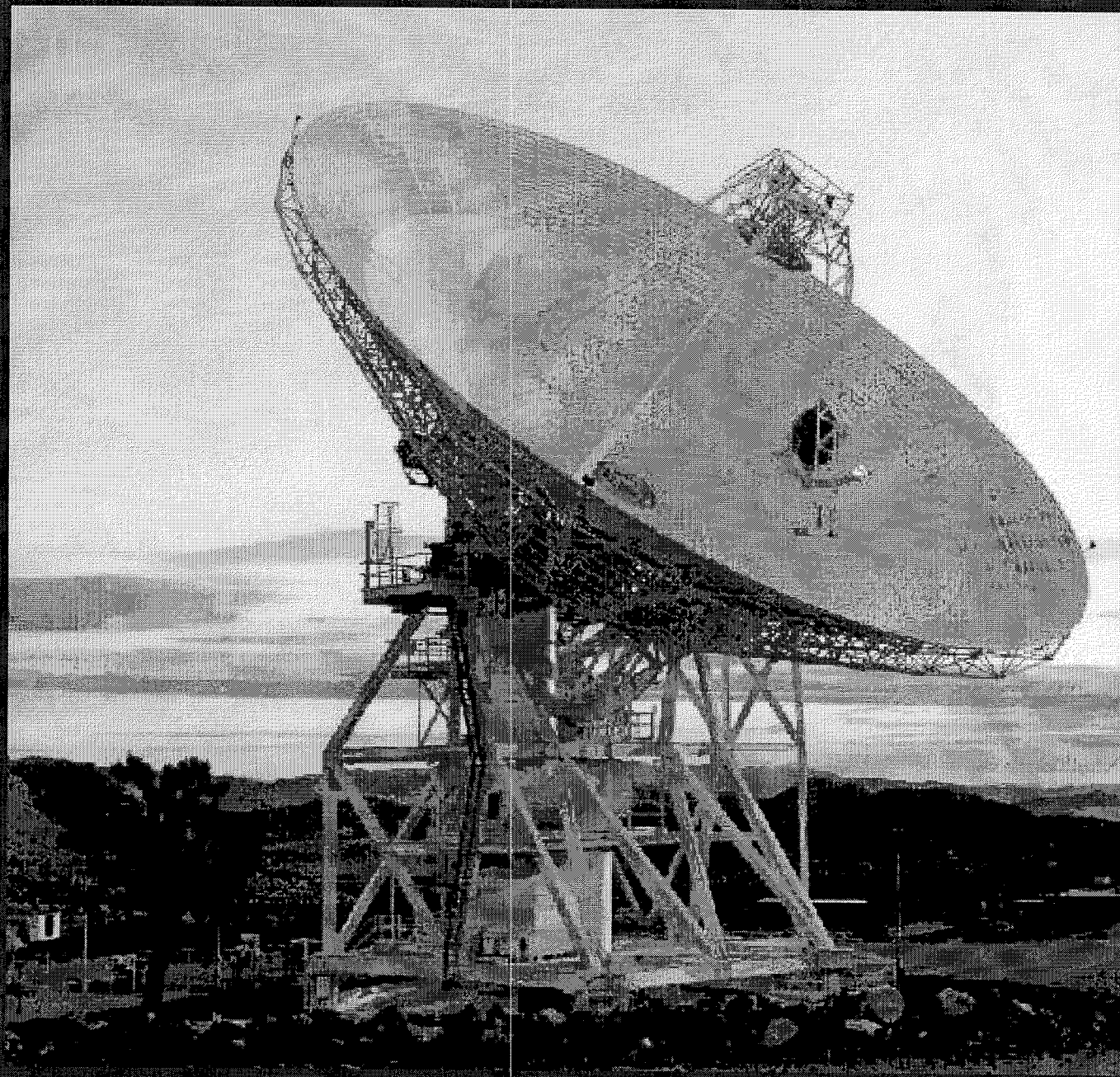
Use the time-varying history of the received frequency to deduce the motion of the spacecraft relative to the DSN



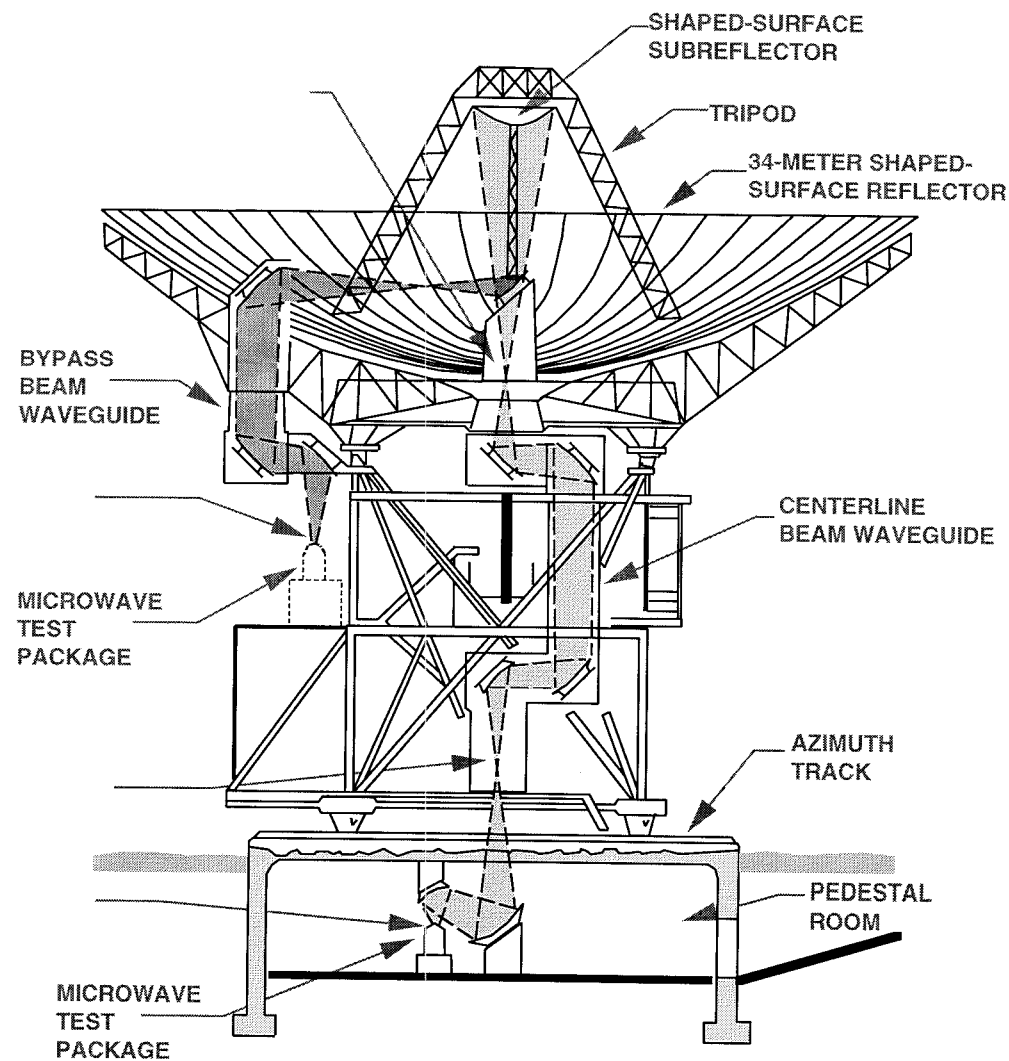


# Hydrogen Maser Frequency Standard





# Deep Space Station (DSS) 13







# Ability to Communicate in Deep Space

- 1) Received Signal Power  $P_r$
- 2) Signal to Noise Ratio ( $P_r/N_o$ )
- 3) How Efficiently SNR is utilized

# Received Signal Power

- $P_r = \rho \mu A_r$

Received Power = Power Flux Density \*  
Effective Aperture of Receive Antenna

- $\rho = \text{EIRP} / 4\pi r^2$

Power Flux Density =  $(P_T G_T) / 4\pi r^2$

# Received Signal Power

## Voyager at Neptune - Parameters

- Voyager Spacecraft
  - $P_T = 21,3 \text{ W}$  (Transmit Power)
  - $G_T = 65.000$  unitless (Gain)
- DSN 70M Antenna
  - $A_r = 3.848 \text{ m}^2$
  - $\mu = 65\%$
- Spacecraft Distance to Earth at Neptune
  - $29 \text{ AU} \cong 4,4 * 10^{12} \text{ m}$

# Received Signal Power

Voyager at Neptune - calculation

- $\rho = \text{EIRP} / 4\pi r^2$
- $\rho = (21,3 \text{ W}) (65.000) / [(4\pi)(4,4 * 10^{12} \text{ m})^2]$
- $\rho = 7,15 * 10^{-20} \text{ W/m}^2$
  
- $P_r = \rho \mu A_r$
- $P_r = (7,15 * 10^{-20} \text{ W/m}^2) (.65) (3.848 \text{ m}^2)$
- $P_r = 1,78 * 10^{-16} \text{ W}$
- An Extremely Weak Signal!

# Signal to Noise Ratio ( $P_r/N_o$ ) - 1

- $N_o$  = Noise Spectral Density
- $N_o = kT$ 
  - $k$  = Boltzmann's constant ( $1.38 \times 10^{-20} \text{ mW/K Hz}$ )
  - $T$  = System Noise Temperature
- DSN's  $T \cong 28,5 \text{ K}$
- $N_o = (1.38 \times 10^{-20} \text{ mW/K Hz})(28.5 \text{ K})$   
 $= 3,9 \times 10^{-22} \text{ W/Hz}$

# Signal to Noise Ratio ( $P_r/N_o$ ) - 2

- $P_r = 1,78 * 10^{-16} \text{ W}$
- $N_o = 3,9 * 10^{-22} \text{ W/Hz}$
- Factor in Losses throughout the link
  - Circuit, pointing, modulation, etc
  - $L = 0.7$  unitless
- $P_r L / N_o = 319.487 \text{ Hz}$

# Signal to Noise Ratio ( $P_r/N_o$ ) - 3

- $P_r/N_o = [EIRP] * [G_r/T_r] * [1/K] * [\lambda/4\pi\rho]^2$

↓

Total Received Power to Noise Spectral Density Ratio

↓

Effective Isotropic Radiated Power

↓

Receiving Antenna Gain/Noise Temperature

↓

1/Boltzmann's Constant

↓

Wavelength & Geometry

# Signal to Noise Ratio ( $P_r/N_o$ ) - 4

## Example: Isotropic Backyard Receiver

- $P_r/N_o = [EIRP] * [G_r/T_r] * [1/K] * [\lambda/4\pi\rho]^2$
- Challenge:
  - Receive a signal from Mars from Spacecraft Low Gain Antenna
  - Backyard receiver has ambient system noise temperature
  - Gain is unity for isotropic antenna
- $P_r/N_o = [10W] * [1/300K] * [10^{23}W/K \text{ Hz}] * [2.2*10^{-28}]$
- $P_r/N_o = 7*10^{-7} \text{ Hz}$



# Signal to Noise Ratio ( $P_r/N_o$ ) - 5

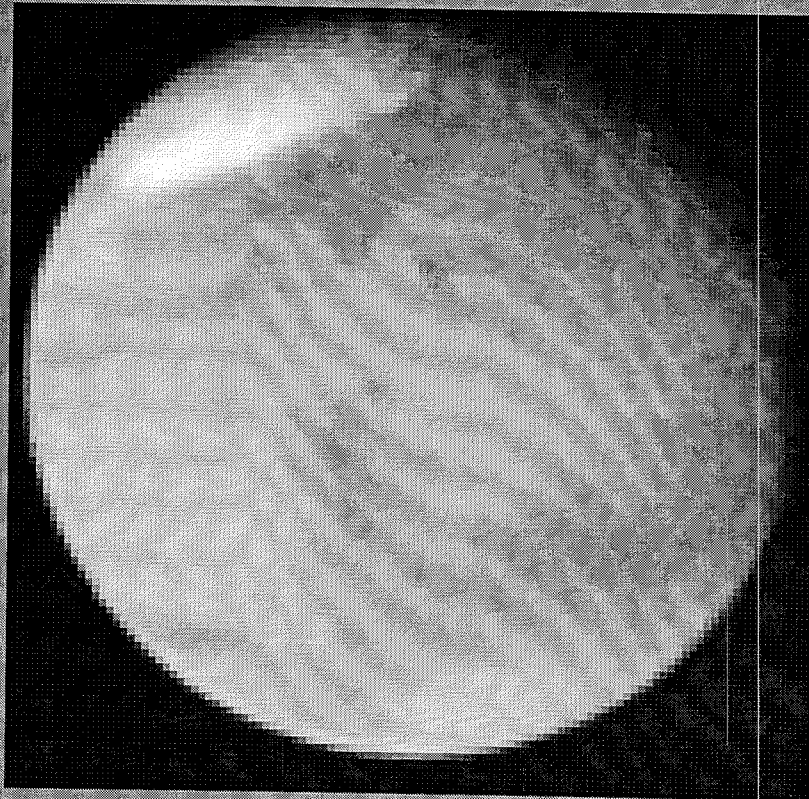
Example: DSN cryogenically cooled Receiver/70M antenna

- $P_r/N_o = [EIRP] * [G_r/T_r] * [1/K] * [\lambda/4\pi\rho]^2$
- Challenge Met:
  - Receive a signal from Mars from Spacecraft Low Gain Antenna
  - DSN receiver has system noise temperature of  $\cong 30$  K
  - 70M Antenna Gain is  $\cong 25$  Million over Isotropic antenna
- $P_r/N_o = [10W] * [10^{7.4}/30K] * [10^{23}W/K \text{ Hz}] * [2.2*10^{-28}]$
- $P_r/N_o = 184 \text{ Hz}$
- Comparison of Reception Capability  $= 2,5 * 10^8$

# How efficiently SNR is utilized

- How much telemetry can be returned is a function of:
  - Link SNR available
  - The BER/FER required on the link ( $E_b/N_o$  to FER curves)
    - » Dependent upon sensitivity of the data types to errors
    - » Typical telemetry link specified at  $1 * 10^{-6}$  BER or  $1 * 10^{-4}$  FER
    - » The advent of Link Retransmission mechanisms will change operations
  - Efficiency of the link dependent upon:
    - » Coding & Modulation chosen
    - » Coding gain from Forward Error Correcting Codes
    - » Move towards Turbo Codes and Bandwidth Efficient Modulation
  - Amount of Link Margin the project holds in reserve

Next Missions to the Planets  
Telecommunications Summary



From  
2001: Mars  
Odyssey  
To  
2014: Mars  
Sample Return

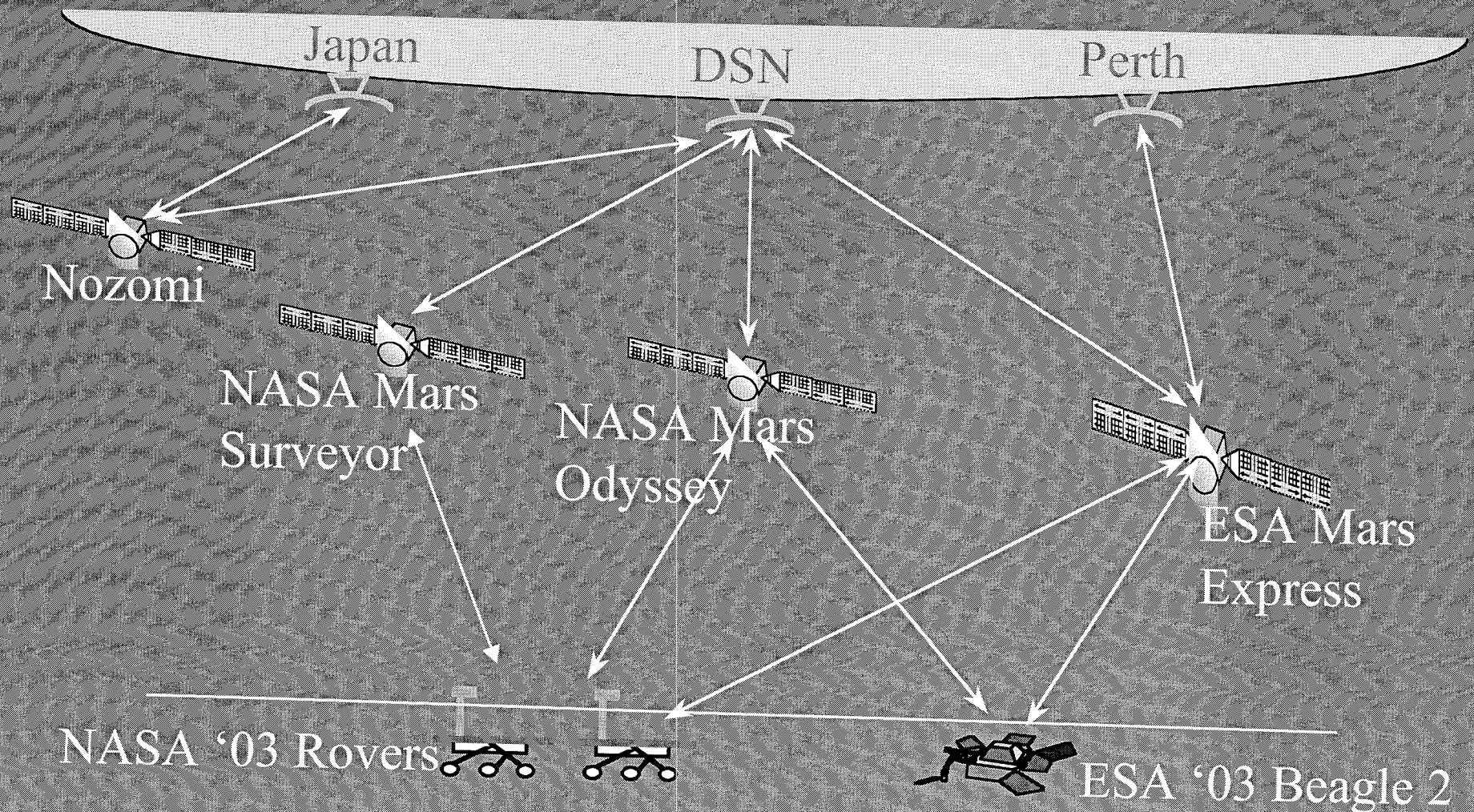


# The Present and the Near Future

- The Voyager missions have been the turnaround point of the exploration of the solar system : from discovery using fly-byes to exploration
- The overall number of missions decreased from the '70s but is increasing the complexity and the capability of the spacecraft
- The data return from each mission is dramatically increasing. The deep space link moving from S (2GHz) to Ka (32 GHz) band.



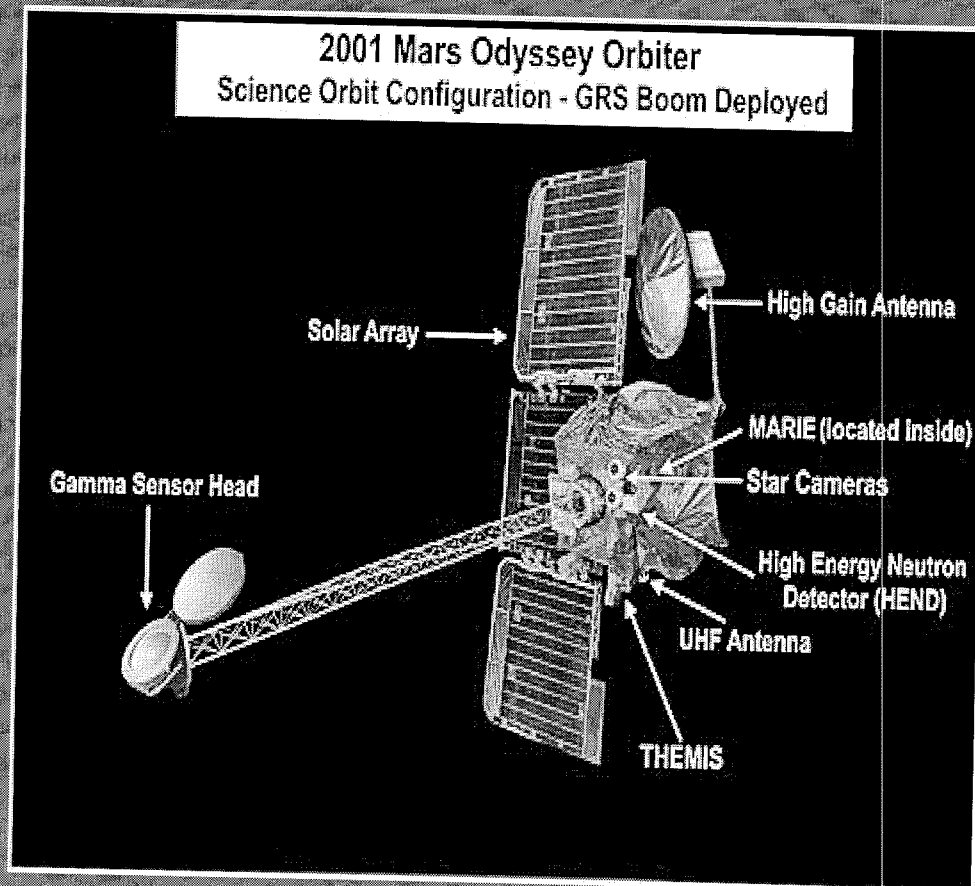
# Mars Scenario 2003-2006





# Mars Odyssey

2001 Mars Odyssey Orbiter  
Science Orbit Configuration - GRS Boom Deployed



- **Primary mission:**  
1 Martian year (orbit insertion: 23-10-01)
- **Extended Mission:**  
1 Martian year
- **Orbit:** 400Km polar, circular and sun-synchronous



# Mars Odyssey: Deep Space Link

- Deep Space Link Frequency: X band
- RF Power: 15W
- Data rate:
  - forward link: 125-2000bps
  - return link: 28-110kbps
- Near Continuous Availability on DSN 34m (BWG) or 70m antennas
- 1.6m High Gain Antenna

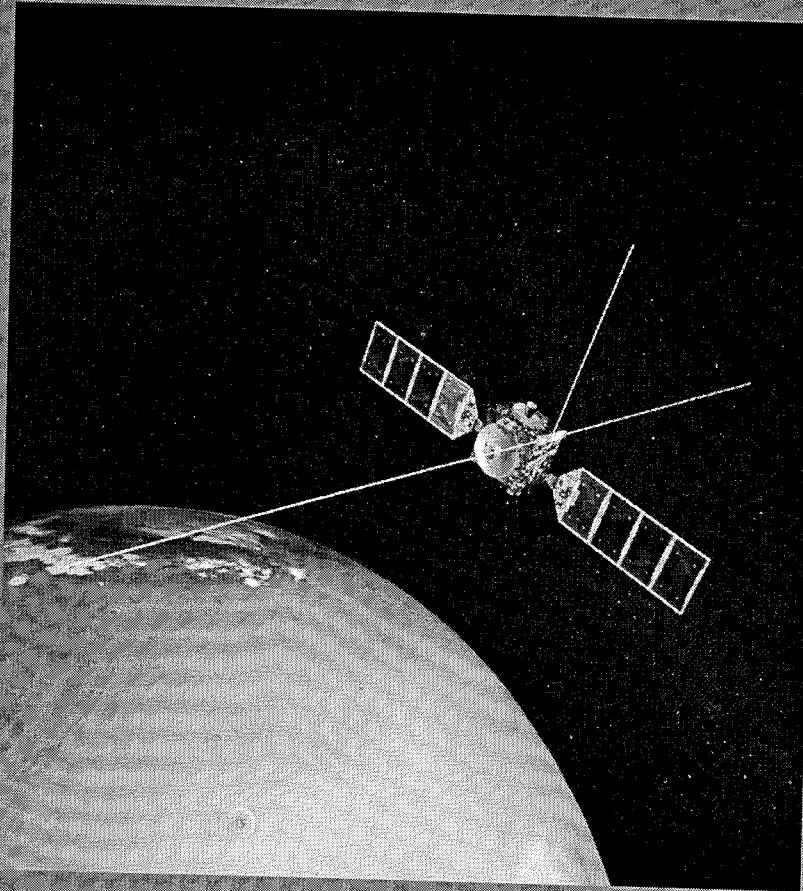


# Mars Odyssey: Proximity Link

- Proximity Link Frequency: UHF
- RF Power: 10W
- Data Rates for forward and return link: 8, 32, 128, 256kbps
- Polarization: RHCP
- Modulation: PCM/Bi-Phase/PM with residual carrier
- Coding: uncoded or Convolutional (7,1/2)
- Antennas: Quadrifilar Helix



# Mars Express



- **Primary mission:**  
Dec 03-Nov 05
- **Extended Mission:**  
Nov 05-Jun 08
- **Orbit: elliptical near polar**
  - **Initial:**  
apoapsis = 11559Km  
periapsis = 258.9Km
  - **After 440 days:**  
apoapsis = 10107Km  
periapsis = 298.4Km



# Mars Express: Deep Space Link

- Deep Space Link Frequencies: S and X band
- RF Power: 5W in S-band and 30W in X-band
- Data rate:
  - forward link (S or X band): 125kbps
  - return link (S/X band): 10-50kbps (125kbps?)
- Coverage: from Perth 32m and Sardinia 64m (starting from late '05); DSN coverage requested for critical maneuvers
- 1.6m High Gain Antenna

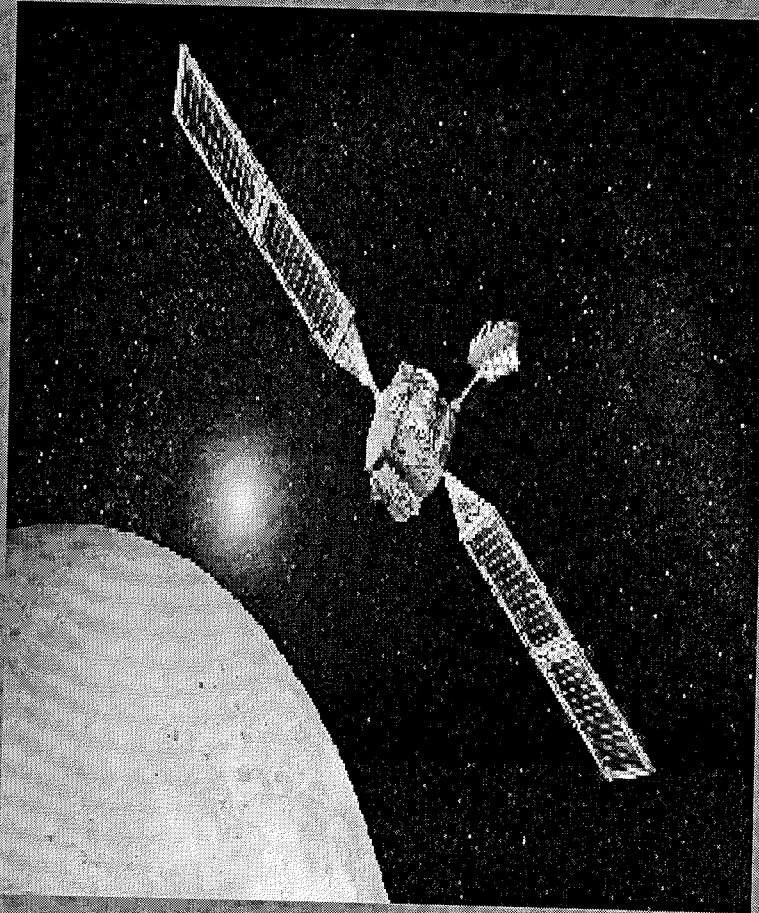


# Mars Express: Proximity Link

- Proximity Link Frequency: UHF
- RF Power: 5 or 10W
- Data Rates:
  - forward link at 2, 4, 8kbps
  - return link at 2, 4, 8, 16, 32, 64, 128kbps
- Polarization: RHCP
- Modulation: PCM/Bi-Phase/PM with residual carrier
- Coding: uncoded or (7,1/2)
- Antennas: Dual Patch



# Nozomi



- **Primary mission:**  
Jan 04-Nov 06
- **Extended Mission:**  
Nov 06- Jan 09
- **Orbit: highly elliptical**
  - apoapsis = 50000Km
  - periapsis (initial) = 300Km
  - periapsis (final) = 150Km
  - orbital period = 38.5h
  - inclination = 170deg



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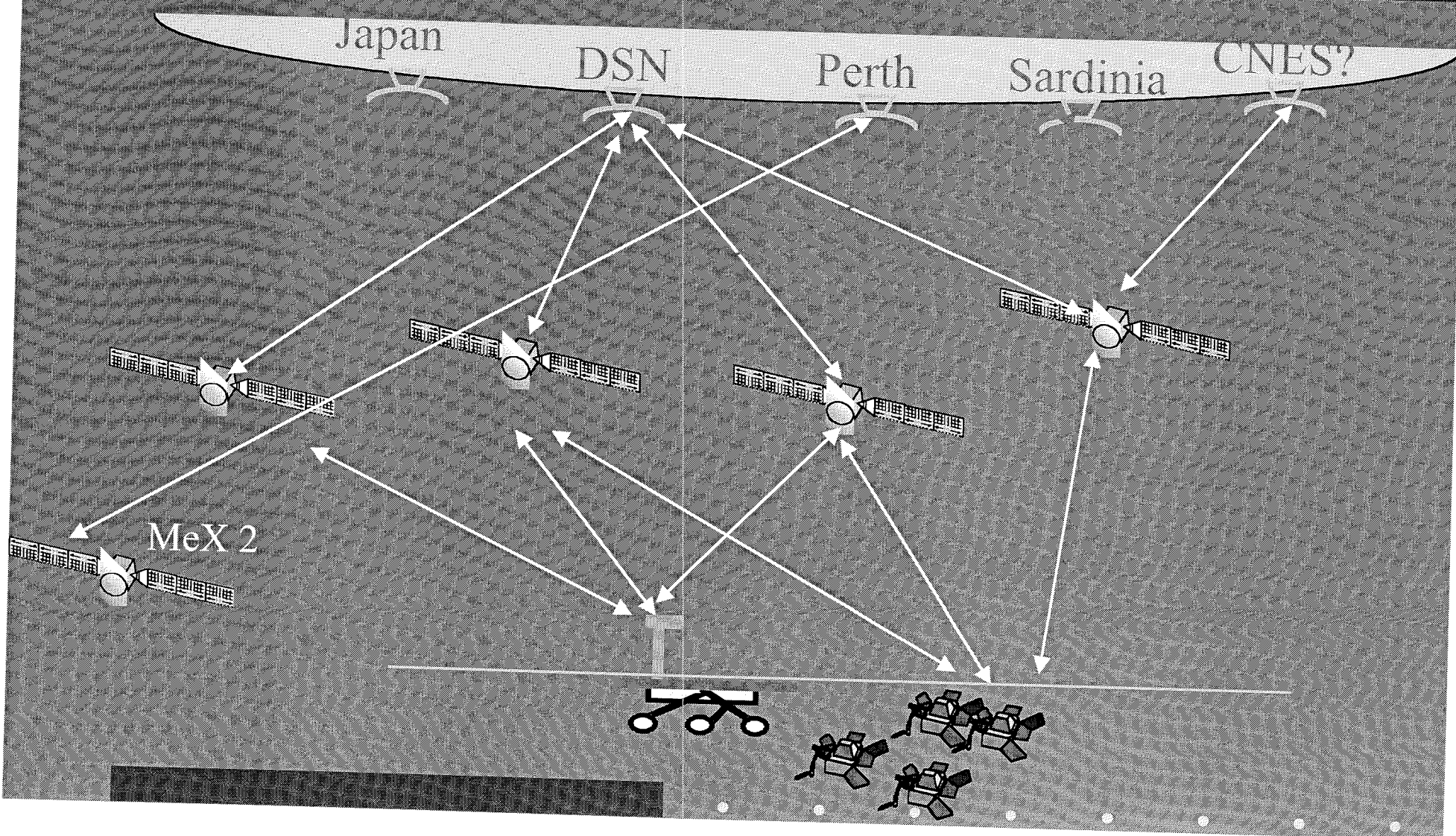
# Nozomi: Deep Space Link

- Deep Space Link Frequencies: S and X band
- RF Power: 2.5W
- Telemetry rates: 2.048 - 32.768kbps
- Coverage: continuous during its primary mission using DSN 34m or 70m (Goldstone and Madrid) and a Japanese ground station
- 1.6m High Gain Antenna

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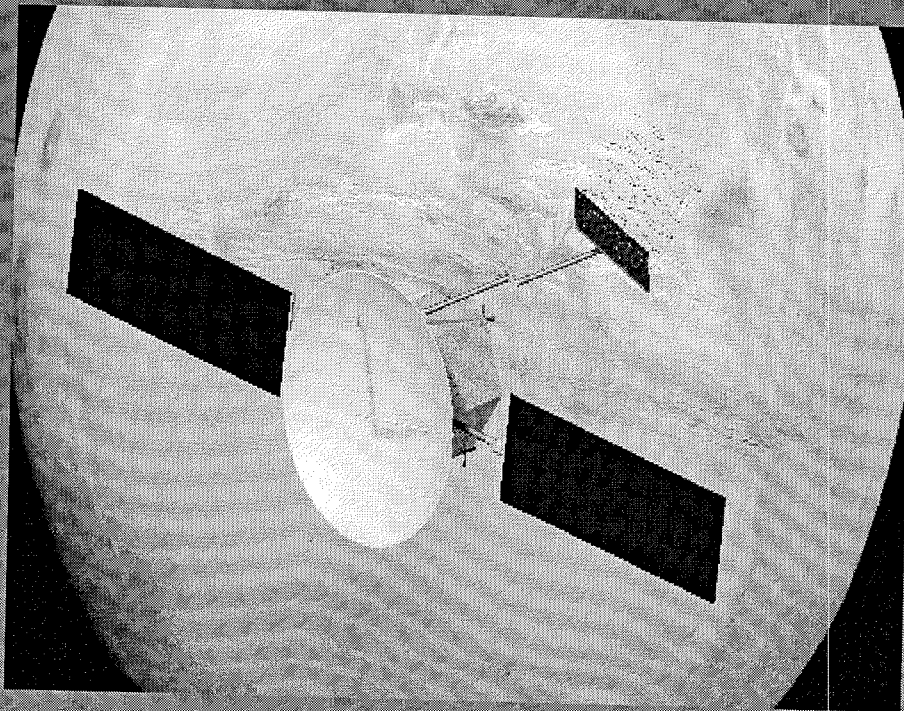


# Telecom Scenario 2006-2009





# Mars Reconnaissance Orbiter



- Primary mission:  
3 Martian years
- Extended Mission:  
2 Martian years
- Orbit: polar and sun-synchronous
  - Apoapsis: 400Km
  - Periapsis: 200Km



# MRO: Proximity Link

- Proximity Link frequencies: UHF (390-405MHz and 435-450MHz sub-bands) X band
- RF Power: 1-10W (selectable)
- Return data rates: 1, 2, ... 512Kbps
- Polarization: RHCP
- Antennas (mounted on a 2m boom):
  - at UHF: 2 low omnidirectional (1 nadir, 1 zenit looking) and 1 medium gain
  - at X band: 1 nadir-looking low gain



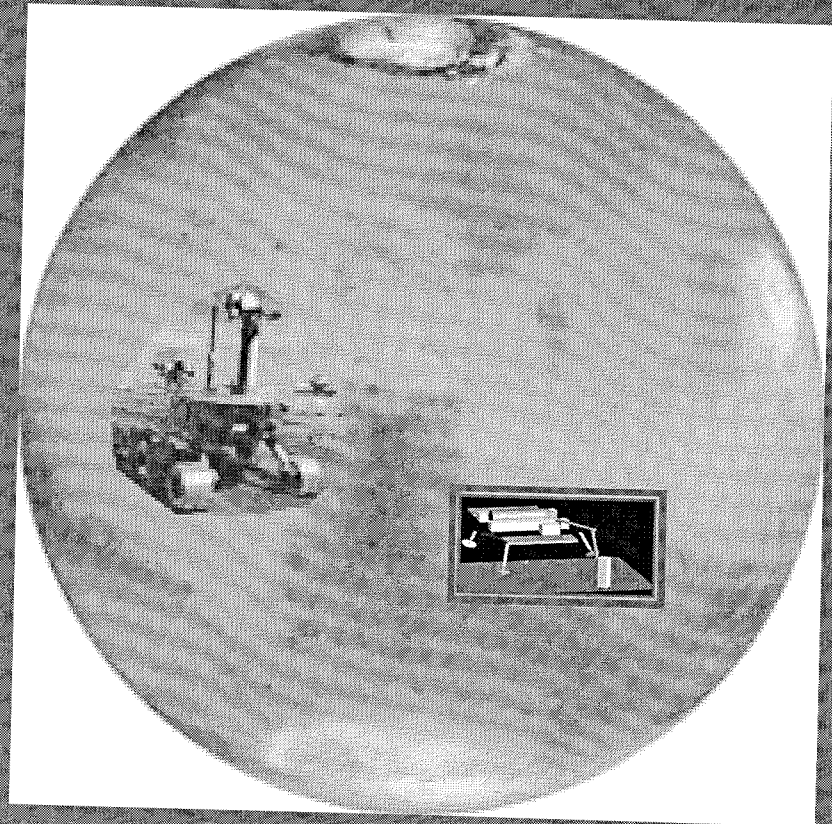
# MRO: Deep Space Link

- Deep Space Link Frequency: X band
- Power: 100W TWTA
- Return data rate: 350kbps – 6Mbps
- Near Continuous Availability on DSN  
34m or 70m antennas
- 2.5 m High Gain Antenna



# In Situ Science : 2009 Smart Lander

- DeeDri : Deep Drill is a drill capable to acquire and handle samples as well as perform science on the surface and within the hole
- IPSE : Italian Package for Science Experiments is a near autonomous miniaturised laboratory capable to house, control and serve a set of instruments in situ science
- Possible participation to Netlanders

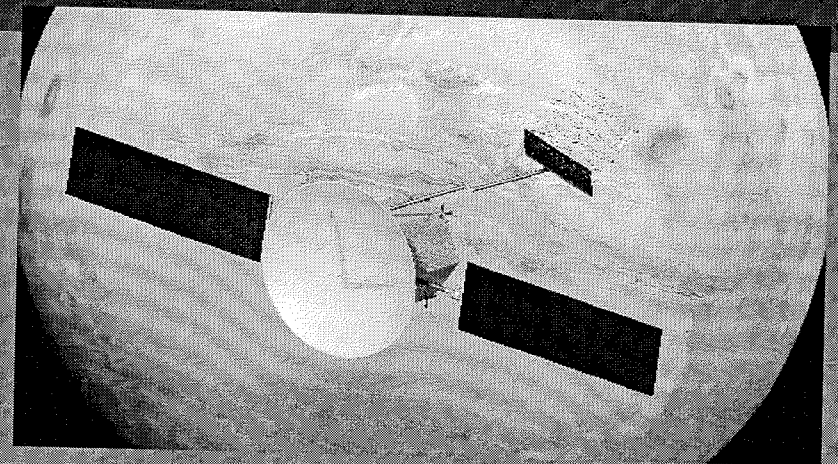




# 2007 Marconi Comm/Nav Orbiter

- **First dedicated Mars telecommunications and navigation orbiter**

- Mid-altitude orbit optimized for comm/nav role, improving performance relative to low-altitude science orbiters
- Will provide comm (EDL and surface relay) and nav (approach nav, surface position, orbital rendezvous) services to other elements of Mars program



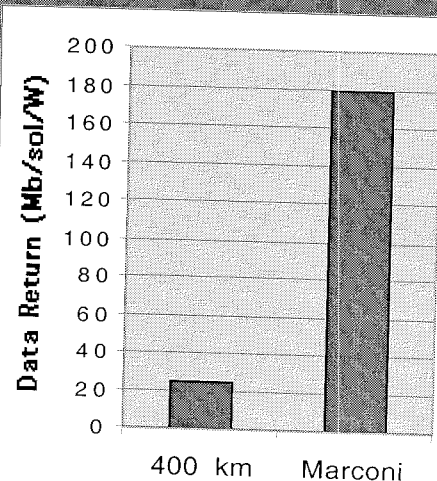
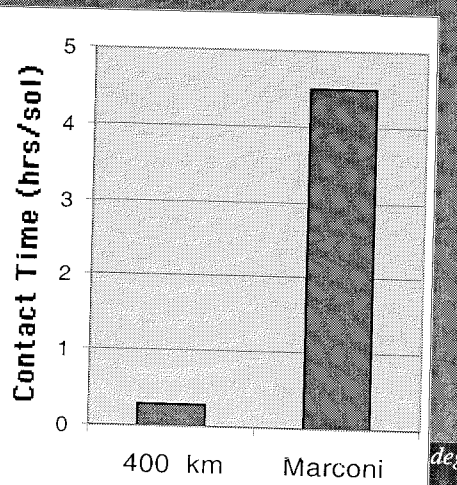
- **Joint ASI/NASA mission**

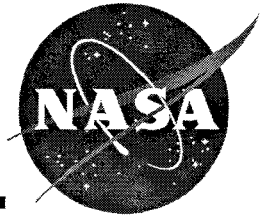
- ASI (Italy) provides:

- Spacecraft
- Assembly Test Launch Operations
- Spacecraft flight operations

- NASA provides:

- Prox link comm/nav payload
- Deep space-specific engineering support
- Prox link service ops





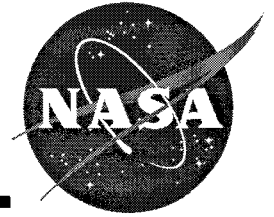
# **NASA's Telecommunications Strategy for Mars Exploration**

**Charles D. Edwards, Jr., David J. Bell, Todd A. Ely,  
Rolf C. Hastrup, Thomas C. Jedrey, Greg J. Kazz**  
Jet Propulsion Laboratory, California Institute of Technology,  
Pasadena, CA 91109, USA



# Outline

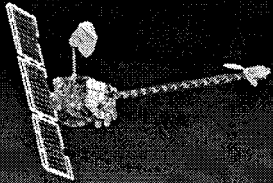
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- **Program Overview**
- **Capability Trades**
  - Telecommunications
  - Data Management/Data Transport
- **Electra - A Standardized Proximity Link Communication/Navigation/Time transfer Payload**
- **Communications Protocols**
- **Summary**

# NASA Participation in Mars Missions

2001



Mars Odyssey

2003

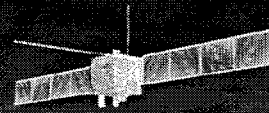
Mars  
Exploration  
Rovers

2005



Mars Reconnaissance  
Orbiter

2007



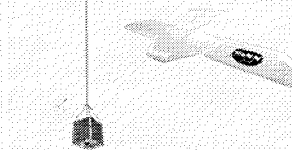
ASI Telecom



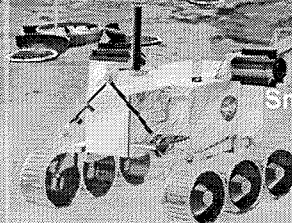
CNES Aerocapture



Aerial Scouts



Netlanders



Smart Lander  
& Rover

2009



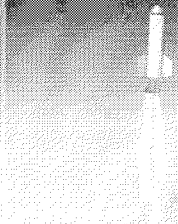
ASI/U.S. SAR

TBD

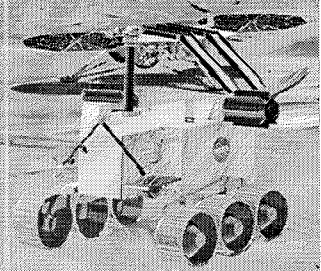
2011



CNES Return



Mars Sample Return  
(with Smart Lander & Rover)

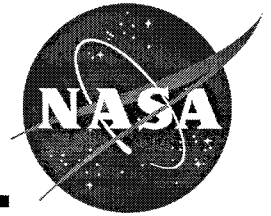


2009

2013

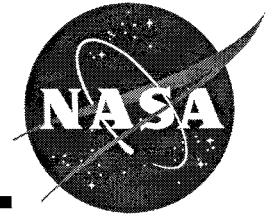
# **Program Drivers on Comm/Nav/Timing Infrastructure**

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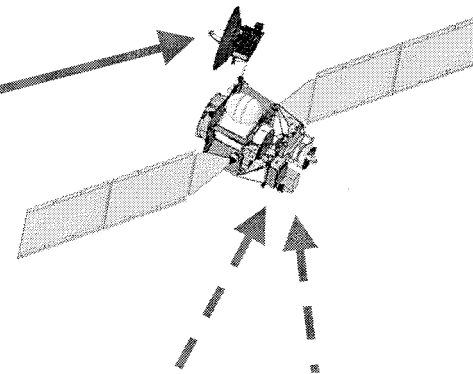
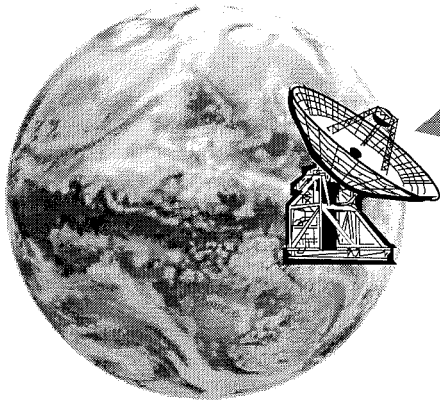
- Increased science data return (e.g., for multi-spectral surface pancam imagery)
- Complexity of Mars Sample Return surface operations, with the resulting need for frequent command cycles and rapid, low-latency engineering data return to support operations planning
- Robust, high-accuracy radio-based approach navigation (e.g.,  $\sim < 1$  km entry knowledge for aerocapture or precision landing)
- Capture of real time engineering telemetry during critical events such as EDL, aeromaneuvering, MAV launch, etc., for feed-forward fault diagnosis in the event of anomaly
- Energy-efficient relay telecommunications for energy- and mass-constrained scout-class missions
- Radio tracking of orbiting sample canister to support in-orbit sample rendezvous
- Surface position determination to support long-range rover navigation

# Mars Telecommunications: Representative Capabilities



## Orbiter Direct-to-Earth Link

- 10 kbps - 1 Mbps to 34m @ 2.7 AU
- Example: MGS
  - 25 kbps
  - 1.5 m HGA
  - 25 W TWTA

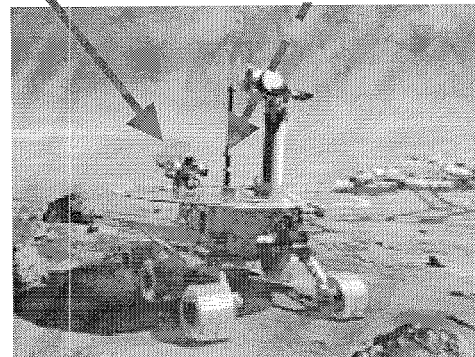


## Lander Relay Link

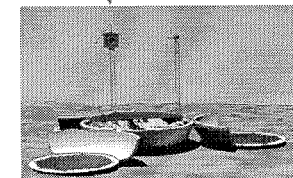
- 100 kbps - 1 Mbps
- Example: MER
  - 128 kbps
  - Omni UHF antenna
  - 10 W SSPA

## Large Lander Direct-to-Earth Link

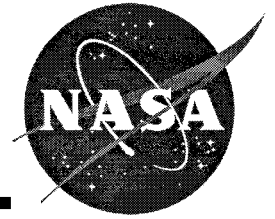
- 1 kbps - 10 kbps to 70m @ 2.7 AU
- Example: MER
  - 2 kbps
  - 28 cm HGA
  - 15 W SSPA



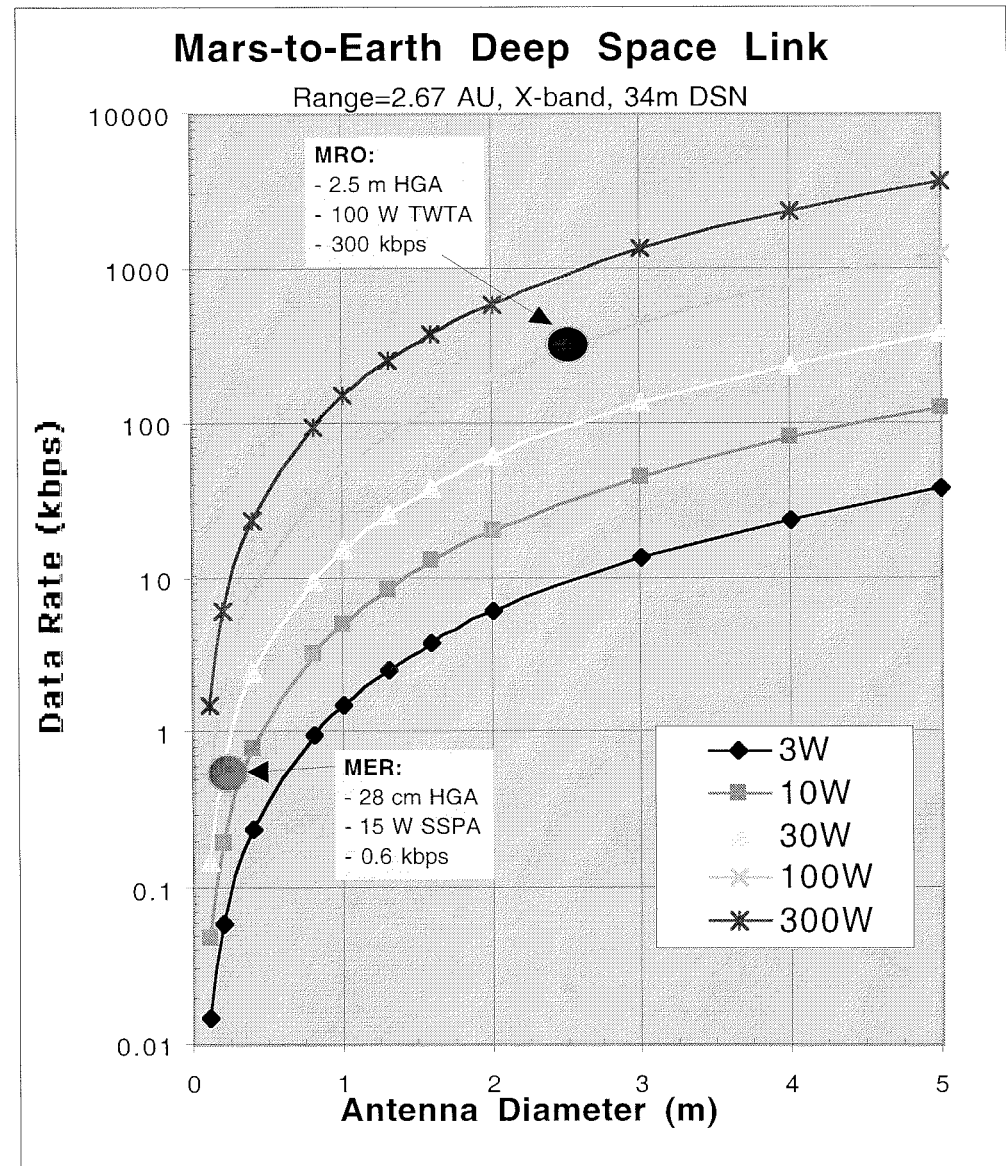
*No DTE capability  
for Scout-class  
landers*



# Direct-to-Earth Communications

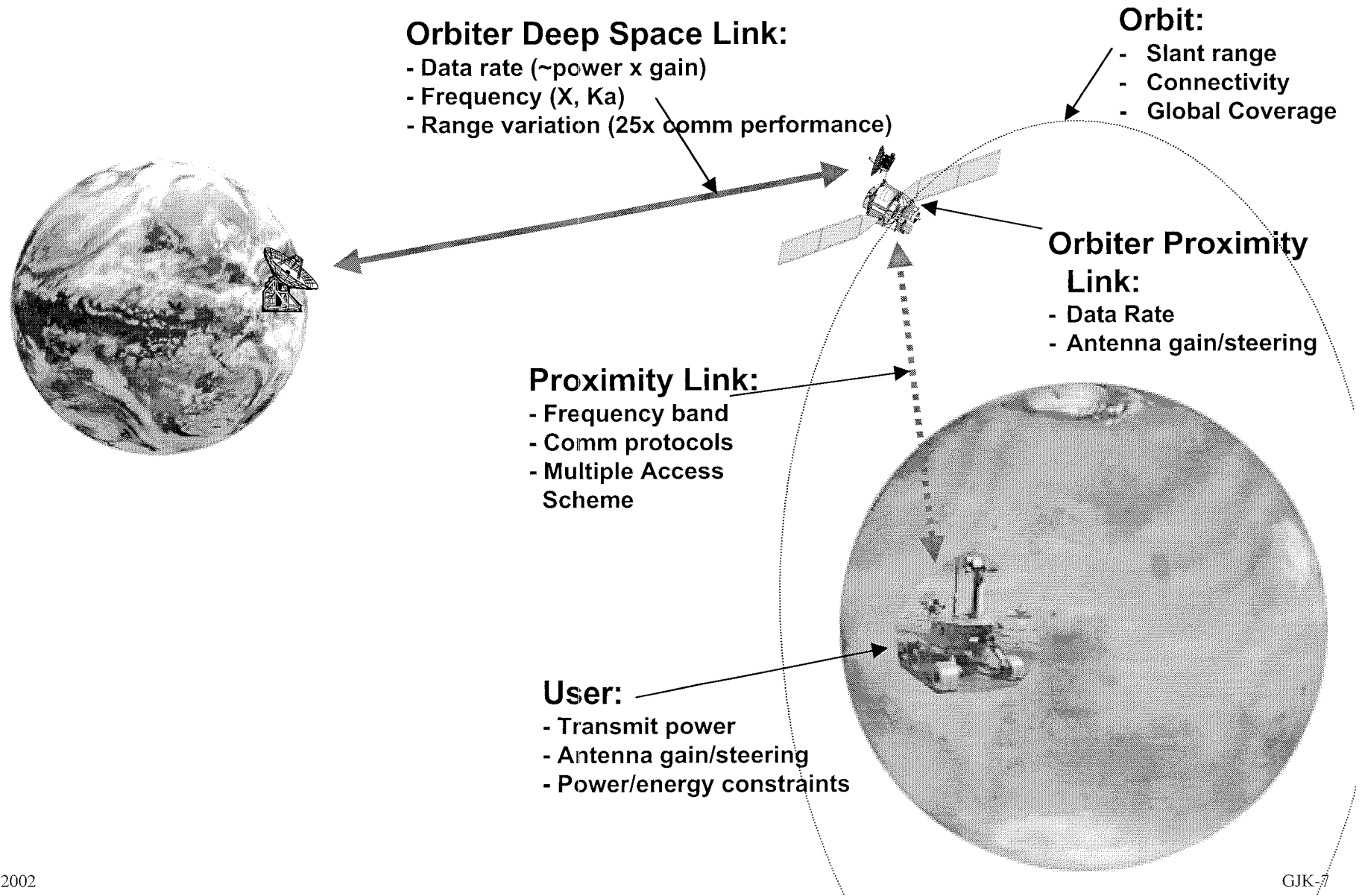
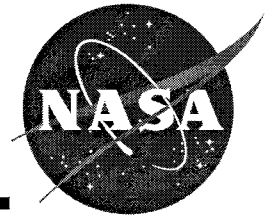


- **Keys to increased DTE link capability:**
  - Transmit power
  - Transmit aperture
  - Frequency (Ka-band offers ~4x improvement over X-band)
  - Earth receive aperture (70m offers ~4x improvement over 34m)
- *Mass, power constraints imply landed DTE capability will always fall well below orbital DTE capability*



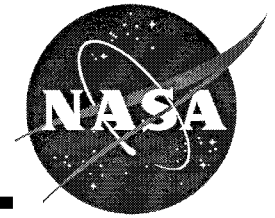


# Key Aspects of Relay Communications



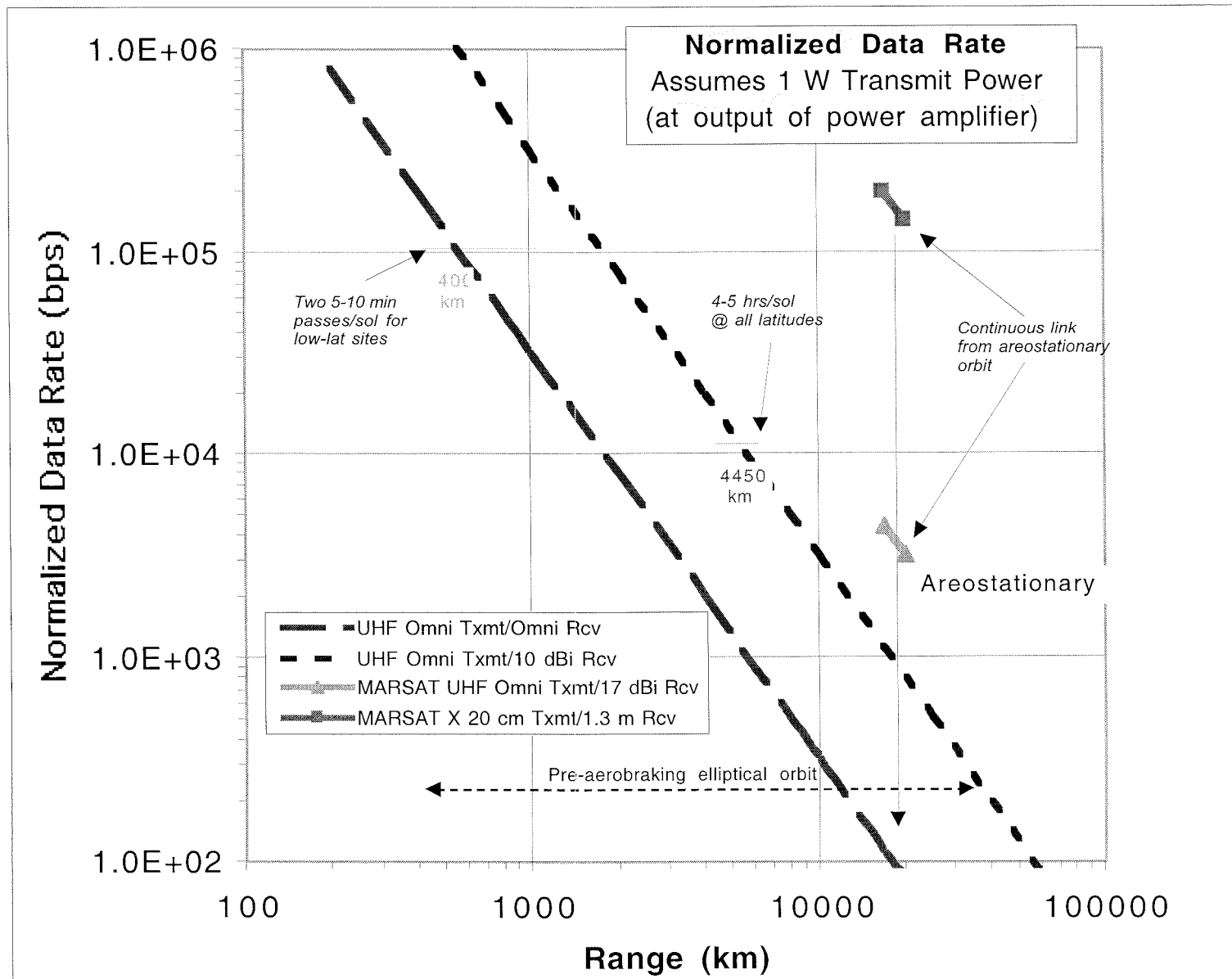
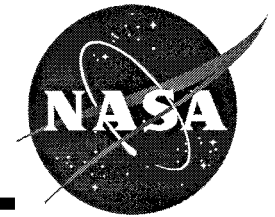
# Proximity Link Characteristics

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- **Omni-to-omni links**
  - Simple ops for lander and orbiter
  - Link performance scales as  $1/\text{freq}^2$
  - Current ~400 MHz UHF band represents balance between link performance and RF component size
- **Omni-to-directional links**
  - Increased orbiter antenna gain can significantly improve link performance
  - To first order, for fixed orbiter aperture size, link performance is frequency-independent
  - However, orbiter antenna pointing requirements scale with frequency
- **Directional-to-directional links**
  - Opens possibility for very high link performance, even over long slant-range links
  - Requires antenna pointing at both ends of link
  - Link performance scales as  $\text{freq}^2$

# Proximity Link Communications

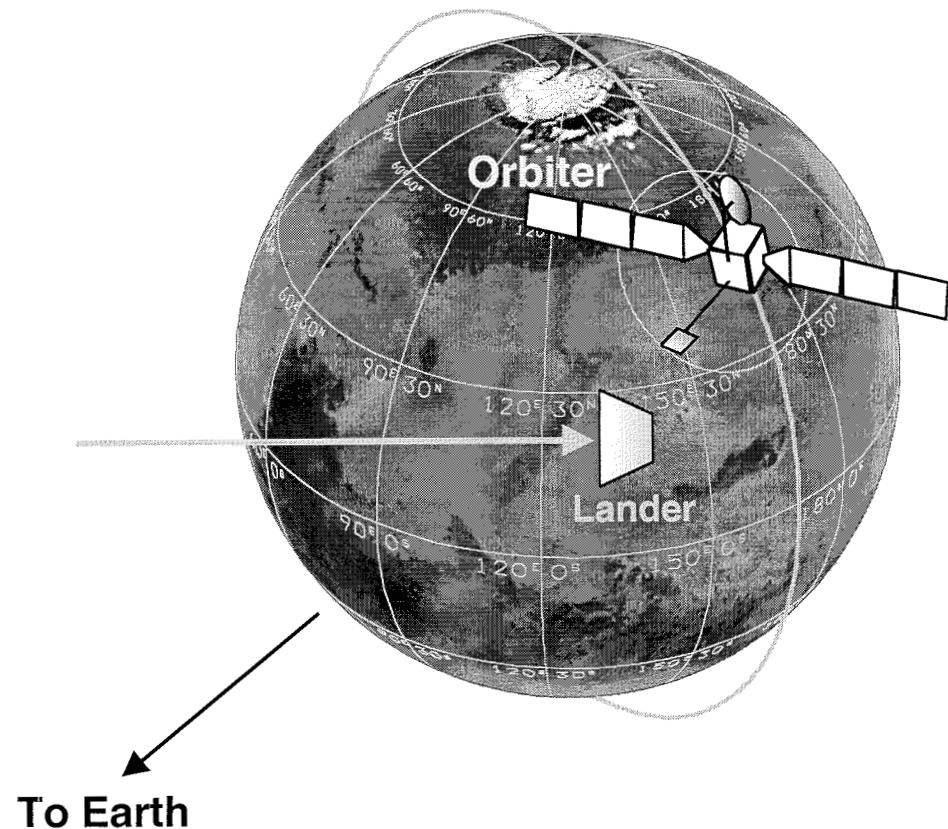




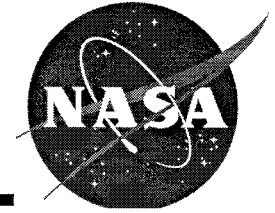
# Critical Event Communications



- **Program policy is to ensure realtime communications for critical mission events**
  - Entry, Descent, and Landing
  - Mars Ascent Vehicle Launch
  - Aerocapture MOI
- **Options:**
  - DTE “semaphores” can provide ~ 1 bps capability
  - High-rate prox link (will be required to characterize more complex 2nd-gen systems)
    - Infrastructure orbiters
    - Converted cruise stage
    - Black box

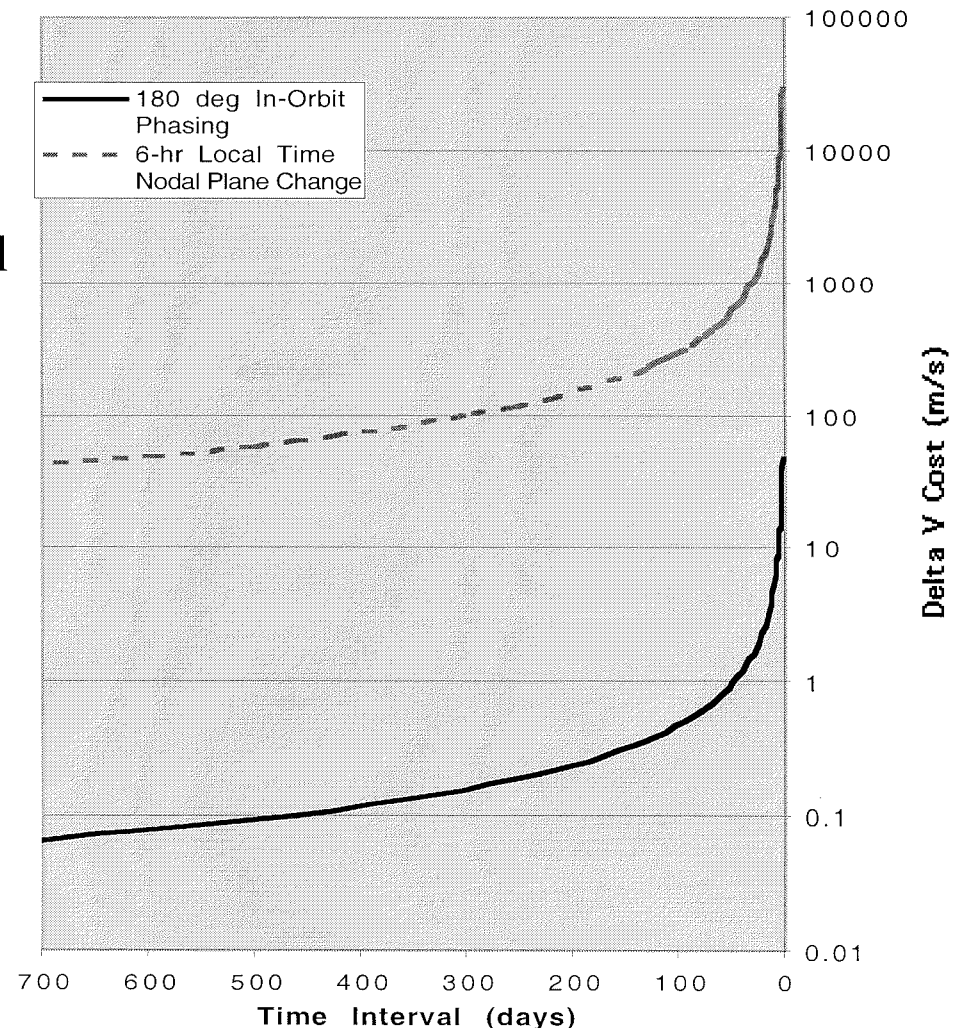
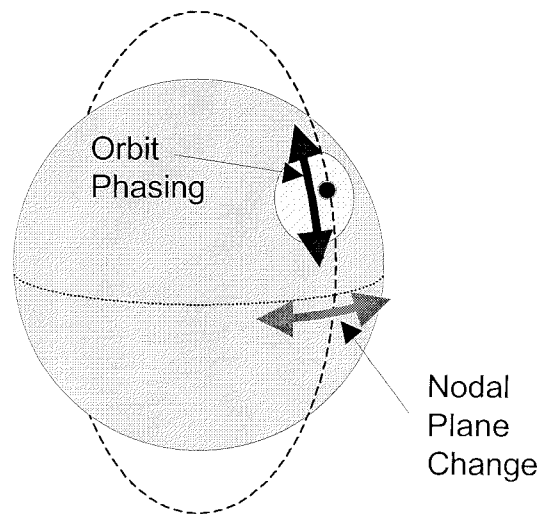


# Orbital Changes to Support EDL Communications

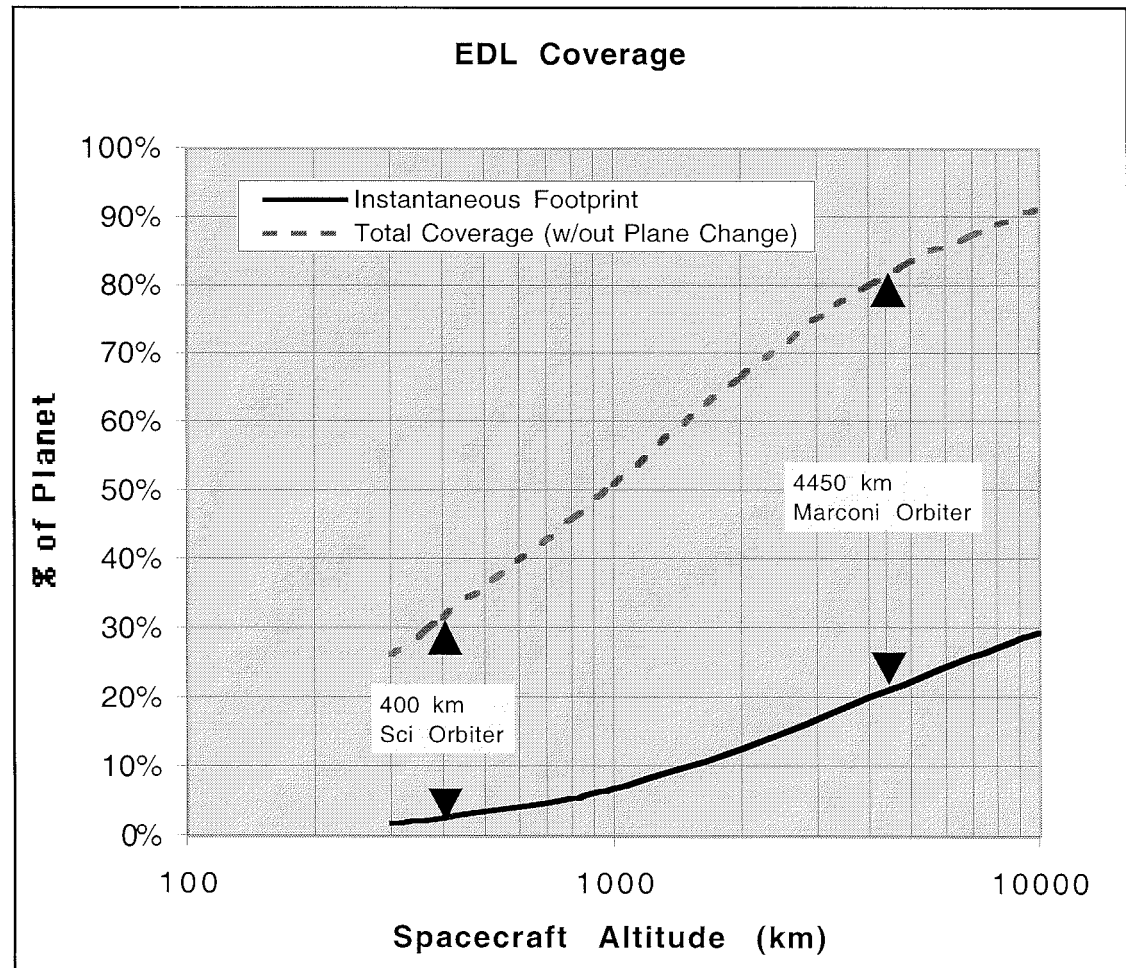
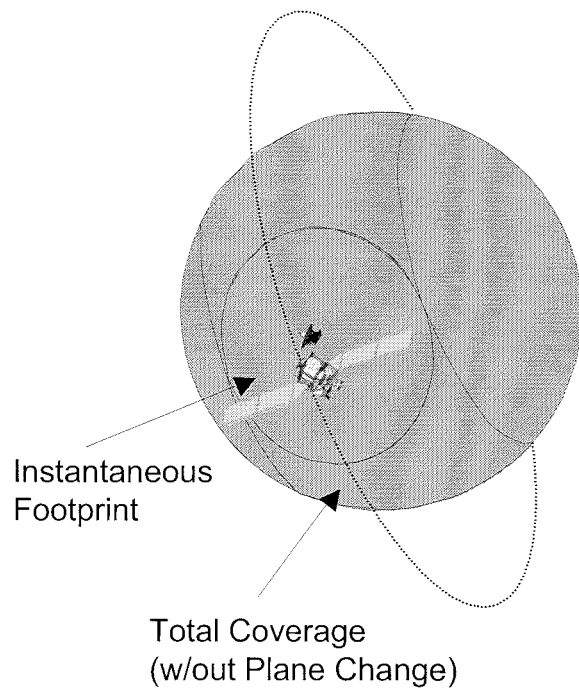
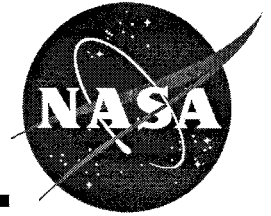


## Orbit Changes for EDL Support

- Use of low-altitude science orbiter for EDL comm relay requires orbit adjustment to ensure EDL visibility
- Preliminary analysis of  $\Delta V$  partial derivatives
  - In-plane orbit phasing:  $\sim 0.26$  m/s per deg/day
  - Nodal plane change:  $\sim 326$  m/s per deg/day

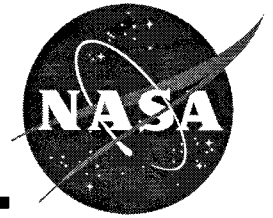


# EDL Coverage





# Key Aspects of Relay Navigation



## Precision Approach Navigation

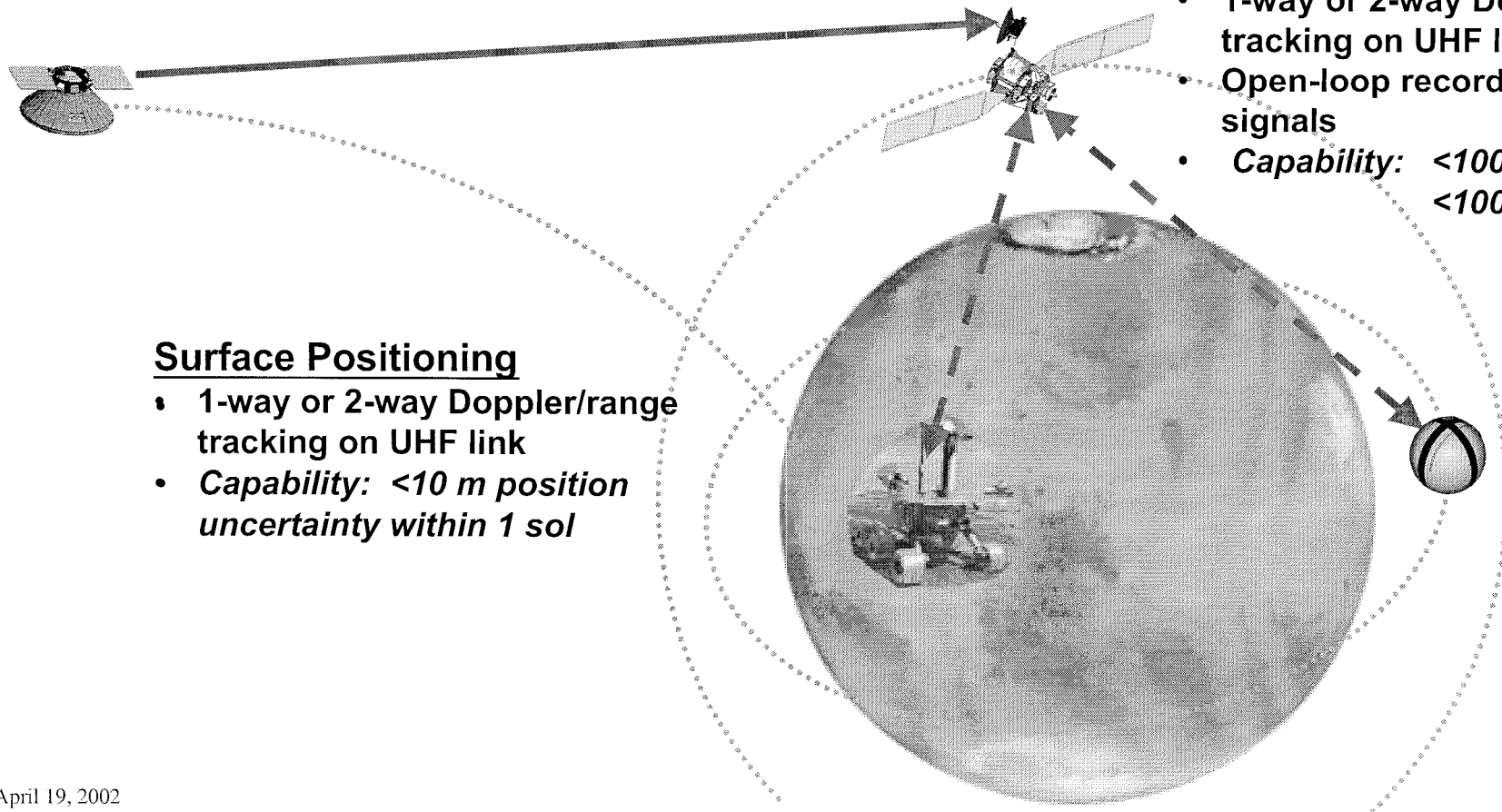
- X-band Doppler on HGA link between approach s/c and orbiter
- *Capability: <0.5 km B-plane error @ E-1 day*

## Orbiting Sample Canister Tracking

- 1-way or 2-way Doppler tracking on UHF link
- Open-loop recording for weak signals
- *Capability: <100 km 1-way <100 m 2-way*

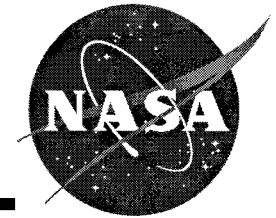
## Surface Positioning

- 1-way or 2-way Doppler/range tracking on UHF link
- *Capability: <10 m position uncertainty within 1 sol*



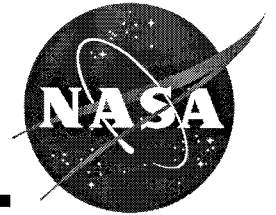
# Trade Space: Relay Orbits

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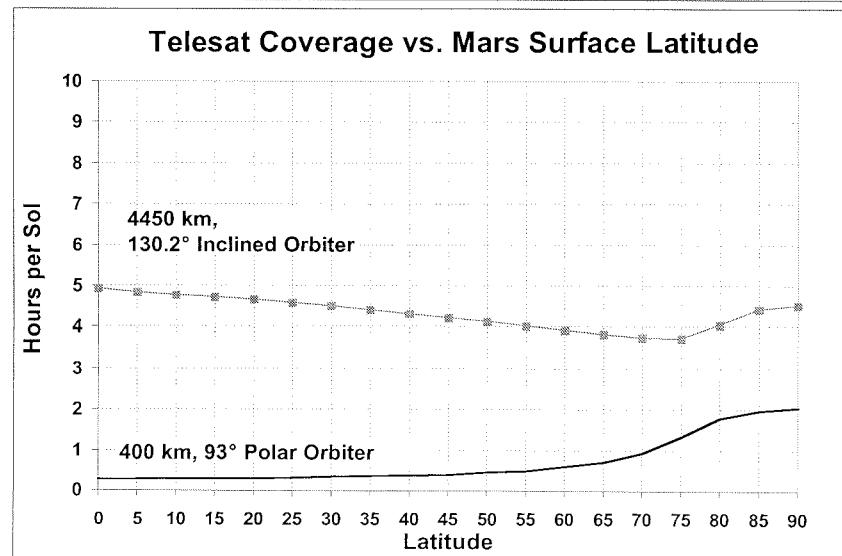
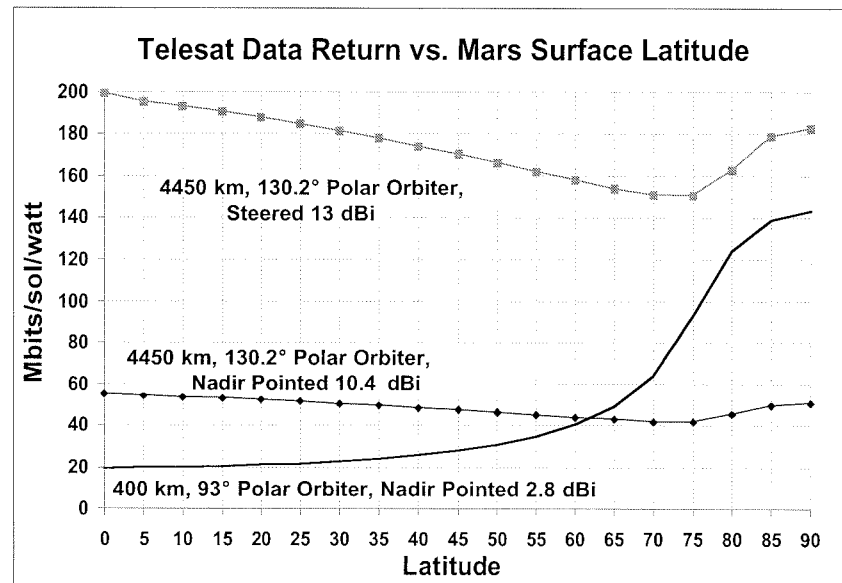
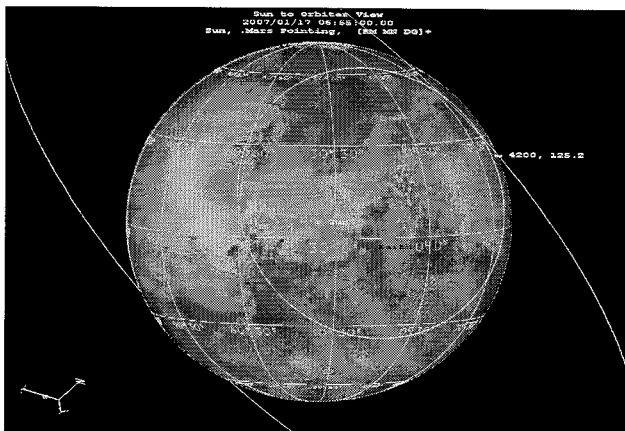


Orbit	Pros	Cons
Low-altitude polar	Global coverage; low slant-range for energy-efficient relay comm, even with simple omni antennas	Very limited connectivity, particularly in equatorial band
Low-altitude equatorial	Frequent contact to equatorial region (can complement polar orbiters); low slant range	No coverage to mid-lat and polar regions
Mid-altitude (e.g., alt = 4450 km, incl = 130 deg)	Global coverage with uniform connectivity from pole to pole; longer and more frequent pass durations	Larger slant range (can be compensated to some extent by increasing orbiter antenna gain)
Areostationary (alt = 17,000 km)	Continuous contact to one region of planet	Large slant range; hi-rate links will require directivity from surface user; no global coverage
"High-Noon" elliptical orbits	Several orbits exist with precession such that apoapse is fixed near local noon, resulting in long daytime passes	Large slant range at apoapse; hi-rate links will require directivity from surface user; variable slant range over orbit increases ops complexity

# Mid-Altitude Orbiters



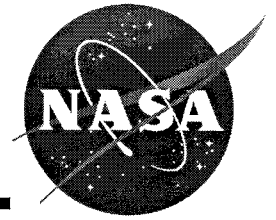
- **4450 km altitude provides increased coverage**
  - Large ground track
  - 4-5 hrs contact per sol, nearly uniform in latitude
  - Multi-Gb/sol with steered orbiter antenna





# Areostationary and Highly Elliptical Orbiters

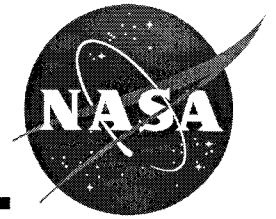
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- **Areostationary**
  - 17,000 km altitude
  - Continuous view of one region of planet (~25% of planet centered about sub-satellite point; no view of polar regions)
  - High-rate (~1 Mbps) continuous relay to Earth with directional surface antenna (satellite at fixed point on sky w.r.t. surface user)
  - Lower-rate (~10 kbps) continuous relay to Earth with simple omni surface antenna
- **HEO**
  - Several “sun-sync” orbits exist with apoapse at a fixed local time (e.g., local noon); long daytime passes
  - Large slant range at apoapse -> similar link considerations as for areo: directional surface antenna req'd for high rate (but now satellite moves on sky w.r.t. surface user)

# Electra Proximity Link Payload

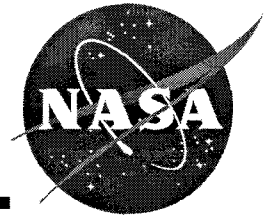
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- **Effort is underway to develop a next-generation standardized Mars proximity link payload**
  - To be flown on all Mars orbiters, starting with MRO'05 - provides *de facto* interoperability and enables gradual implementation of Mars orbital comm/nav/time infrastructure at low incremental cost
  - Flight reconfigurable/reprogrammable over long mission lifetime
  - Greater flexibility (wider range of supported data rates; swappable txmt/rcv bands, multi-channel operation)
  - Improved navigation/timing performance
  - Improved performance (coding, low-loss half-duplex mode, increased PA efficiency, ...)
  - Modularity to allow scaling for low-mass lander/scout applications
  - Portability to facilitate integration with variety of orbiters
  - Self-contained relay functionality (including relay data accountability) for improved testability

# Protocols

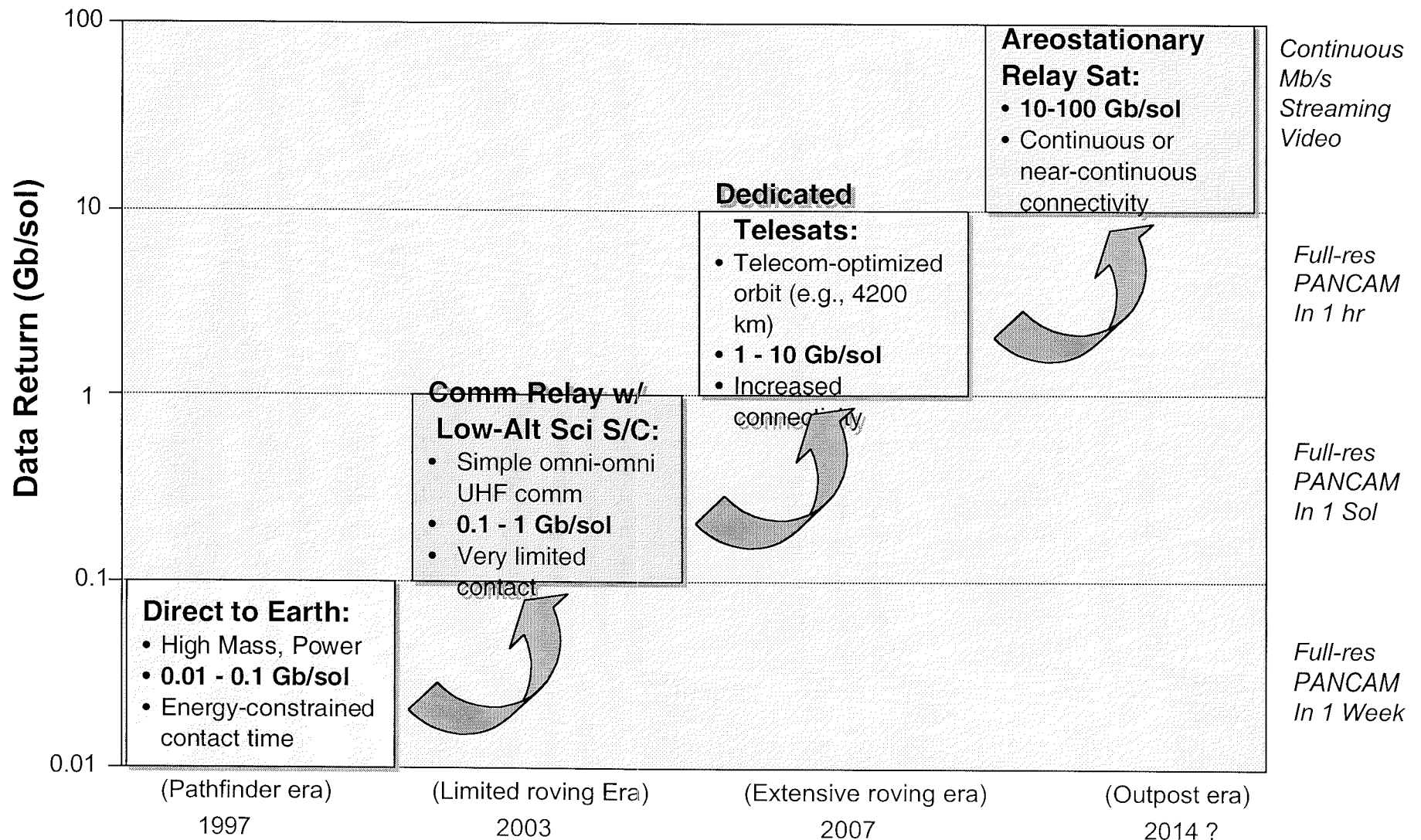
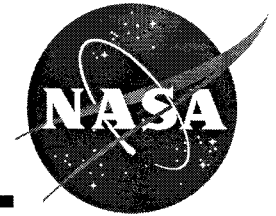
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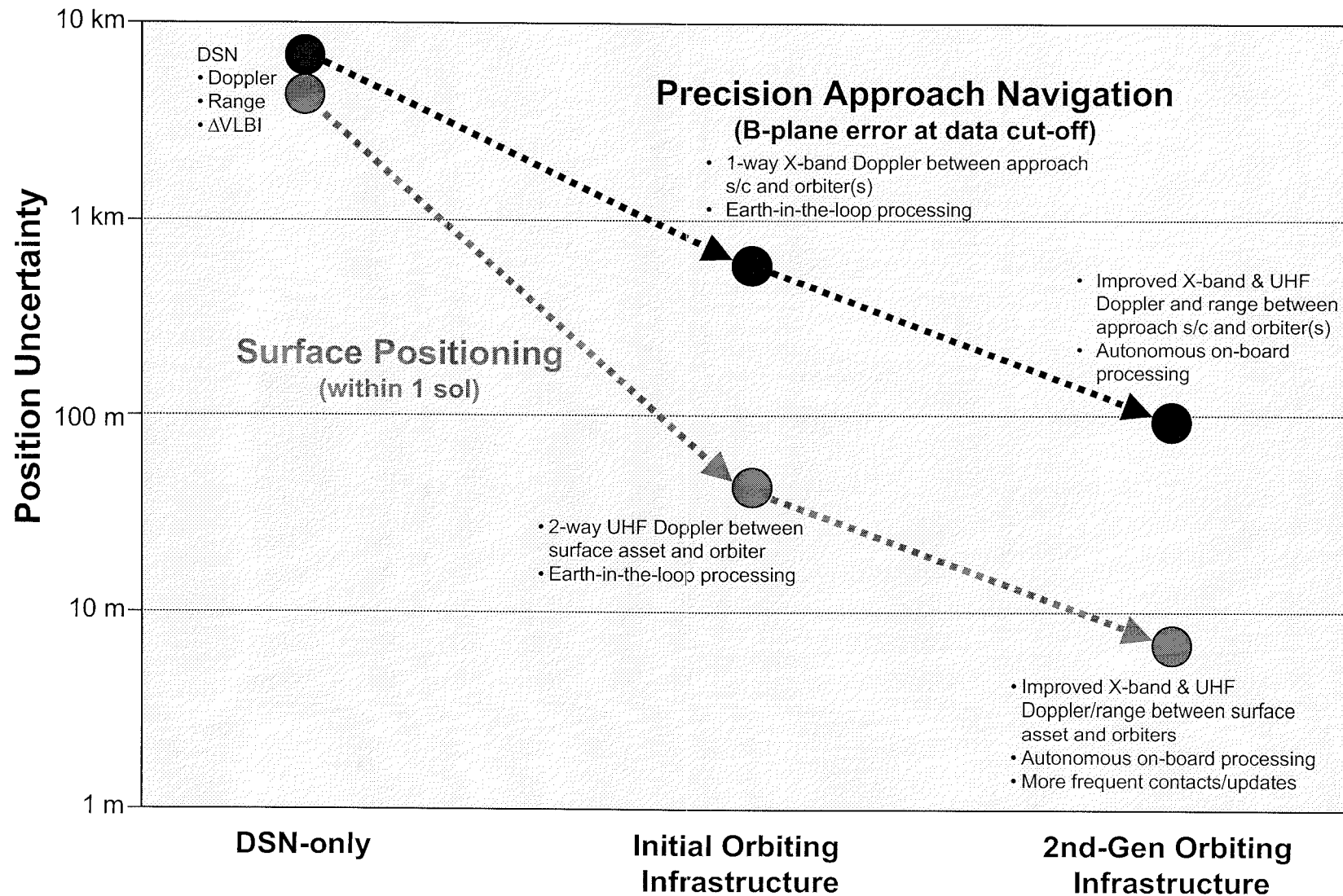
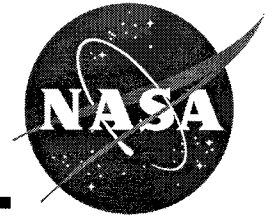
- **CCSDS Proximity-1 Space Link Protocol**
  - Provides standards for the physical and data link layers for Mars proximity communications
  - First implementation on Mars Odyssey
  - Will be key for achieving interoperability among MER A/B, Beagle 2, Mars Express, Odyssey and missions beyond 2003
- **CCSDS File Delivery Protocol (CFDP)**
  - Provides reliable and expedited end-to-end file delivery
  - Addresses unique aspects of deep space communications
    - Long Round Trip Light Times
    - Intermittent connectivity – non persistent links
    - Transaction based
    - Multi-hop store-and-forward relays
    - Custody transfer to minimize onboard storage requirements
- **Standards on the web at [www.ccsds.org](http://www.ccsds.org)**



# Evolution of Mars Telecommunications Capability

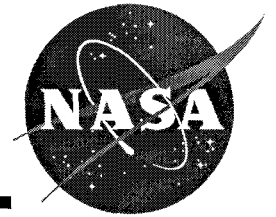


# Evolution of Mars Radio-Based Navigation Capability

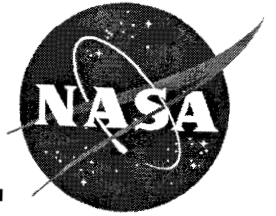


# Some Parting Questions...

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- **How do we manage and operate a heterogeneous collection of orbital relay spacecraft as an integrated Mars comm/nav infrastructure?**
- **What is the science value of increased bandwidth and connectivity?**
  - How would a continuous high-rate areostationary relay change our surface operations concepts?
- **When is it cost-effective to transition to:**
  - Demand access proximity service concept?
  - On-board radiometric data processing?
  - Higher-frequency directional lander links?
- **How should our proximity link standards evolve?**
  - Physical layer
  - Modulation and coding
  - Higher layers of data management
  - Ultimate interface with IPN vision

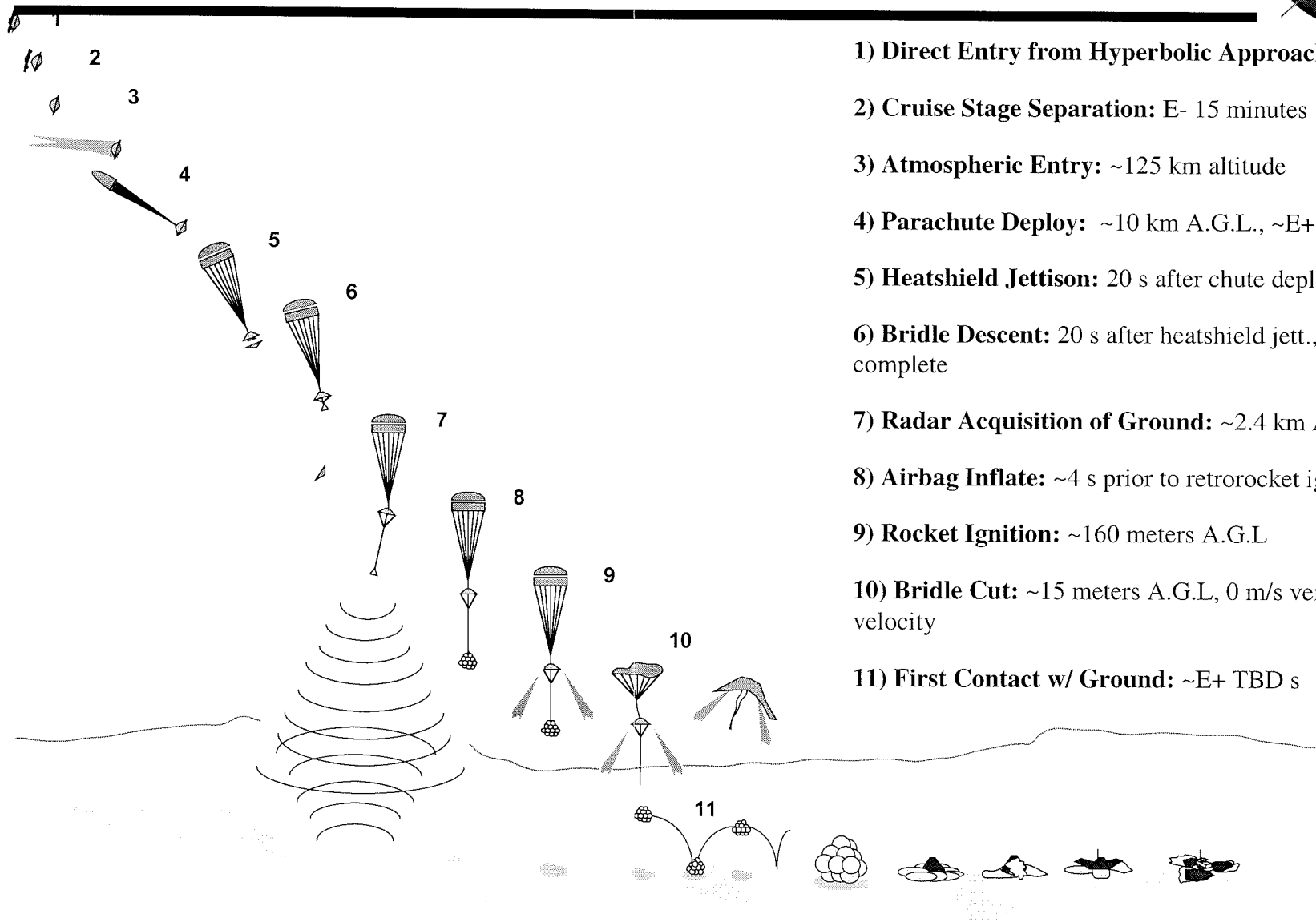
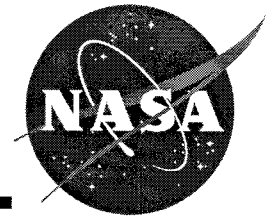


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## **A Real-World Example: MER EDL Communications**



# EDL Sequence of Events Overview



- 1) Direct Entry from Hyperbolic Approach
- 2) Cruise Stage Separation: E- 15 minutes
- 3) Atmospheric Entry: ~125 km altitude
- 4) Parachute Deploy: ~10 km A.G.L., ~E+ TBD s
- 5) Heatshield Jettison: 20 s after chute deploy
- 6) Bridle Descent: 20 s after heatshield jett., 10 s to complete
- 7) Radar Acquisition of Ground: ~2.4 km A.G.L
- 8) Airbag Inflate: ~4 s prior to retrorocket ignition
- 9) Rocket Ignition: ~160 meters A.G.L
- 10) Bridle Cut: ~15 meters A.G.L, 0 m/s vertical velocity
- 11) First Contact w/ Ground: ~E+ TBD s

# EEIS Relay Requirements for Mars Program

formulated for Marsnet

by MM-EEIS group

Section 311 at NASA/JPL

# What are we trying to accomplish?

*EEIS Relay Requirements*

*4/19/2002*

*NASA Mars Program*

- Identify data types, their requirements and data resource management policies
  - Which teams manage what data ?
  - What Data services are provided by Mars Enterprise Elements ?
    - Relay Orbiters
    - IPN-ISD
    - Relay Assets
    - Data service interface requirements
- Identify for each team, and each interface, the performance requirements we need to accomplish to meet the science requirements (level 2) and relay operational objectives
- Identify the End-End data accountability requirements and processes
- Identify the Telemetry Handling and Access requirements
  - including processes and protocols
  - QQCL
- Identify the Timing and Radiometric Service Requirements

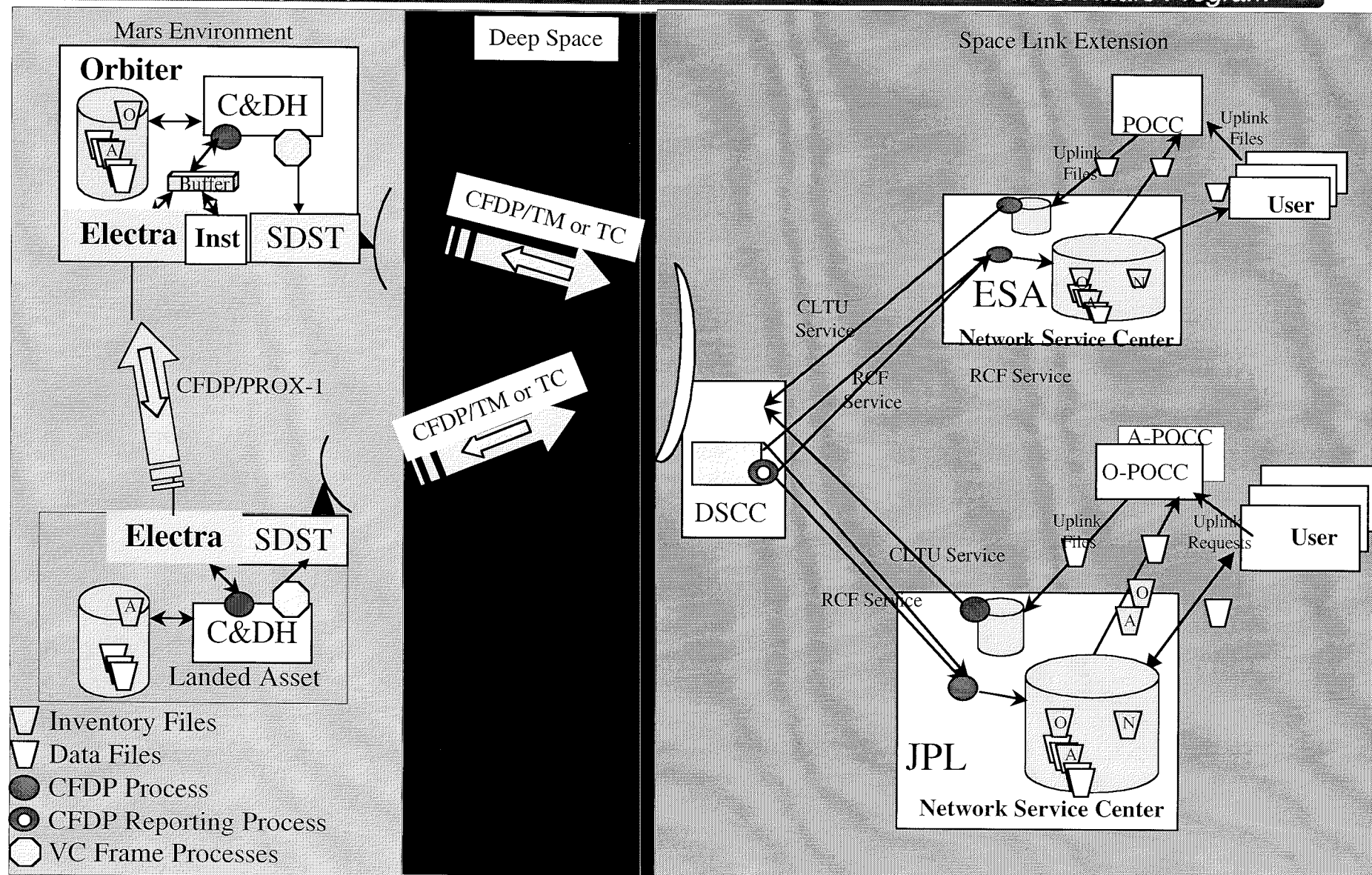
# Mars Network EEIS Context

## Data Flow and Visibility

EEIS Relay Requirements

4/19/2002

NASA Mars Program





# What Data Types are Required?

*EEIS Relay Requirements**4/19/2002**NASA Mars Program*

- **Science and Engineering Data Products**
  - Products are individual named data entities (Named Data Units)
  - E-E Data Product accounting services shall account for all NDUs created for transfer between Enterprise entities.
  - Each Enterprise Element (S/C, Processing center) shall maintain a Product Inventory
    - Product Inventories shall provide the following:
      - Time of product creation
      - Activity associated with product creation
      - Creator of product
      - Status of Product (delivery and completeness)
      - Other Product attributes TBS
- **Stream Data Units**
  - DTE Link shall use CCSDS Packet Telemetry or AOS frames
  - DFE Links shall use CCSDS Telecommand frames
  - Proximity Links (Mars local communications) shall use CCSDS Proximity-1 Protocol
  - CCSDS Packets are used for source data and application message identification
    - Engineering Telemetry Measurements
    - NDU segments used during transfer (e.g. packets containing CFDP PDUs)
    - Objects for model and or data base updates (e.g. catalogs, state models)

# What Data Service Types are Required?

*EEIS Relay Requirements*

*4/19/2002*

*NASA Mars Program*

- Identify and quantify data management and delivery services required
  - Forward Services
    - Named Data Unit Delivery Services
    - CLTU Service
  - Return Services
    - Named Data Unit Delivery Services
    - Stream Data Services
- Identify which teams manage what data
- Identify E-E data management requirements
  - Womb to Tomb accounting and delivery status visibility for acquired data products
- Identify for each team, the performance requirements we need to accomplish to meet the science requirements (level 2) and relay operational objectives
- Identify the Telemetry Handling requirements
  - including QQCL performance requirements

- Virtual Channels
  - Minimum of two Virtual Channels required for DSN SLE RCF Service
    - real time (on-line) delivery service (could use one VC for delivery to each continents distribution center)
    - off-line (up to 24 hour delay) delivery service
- Accounting (received vs projected)
  - DSN accounts for frames received and delivered to AMMOS/Project's Data Mgt System
  - S/C creates and maintains an Inventory of all NDUs (size, source, activity, creation, other attributes)
    - sends Inventory NDU updates to AMMOS/Project Ops Team for later E-E comparisons
  - AMMOS accounts for packet streams(real time engineering) and Named Data Units products
    - volume comparison with frames received
    - comparison of received NDUs with S/C inventory of NDUs sent
- Three Qualities of Services for NDUs
  - Reliable service requires ground generated ARQ/reports for retransmissions
    - data deleted from storage by custody transfer reports only
  - Best Effort service uses ARQ for a prescribed period
    - data deleted by Custody transfer or after a prescribed period even if not all confirmed
  - Expedited service does not include ARQ (only service available to packet streams)
    - delivers units possibly with deletions
    - data deleted from storage with formulation of telemetry
- Time Correlations
  - Network time accuracies including Time correlation with Landers TBD



# Science Products and Relay Data Services-1



*EEIS Relay Requirements*

*4/19/2002*

*NASA Mars Program*

Science Products and Relay Data are handled exclusively as NDU(s)

- Orbiter data capture and relay services
  - Minimally the received data are blocked and accounted for as an NDU
    - assumes data are uniquely formatted for instrument unique processing (on-board or on Earth)
      - » Metadata would be created for each NDU
  - Received data that are formatted in CCSDS Packets could be further processed
    - Processing services would be provided by agreement with the Asset/Instrument
      - Packet Services: This service would select packets by their APID for inclusion in a derived NDU(s)
        - Functionality may be needed for different required delivery latencies and/or QOS
        - Metadata would be created for each NDU
      - CFDP Service: This service transformations of the CFDP packets into the NDUs
        - Transaction received metadata is used for each individual transaction NDU received
          - \* Name, size, time of creation, other attributes (e.g. destination, priority (time to live), QOS)
        - NDU will be accounted for an E-E basis
          - \* Accounting begins with inventory unit created in the originating Asset



Science Products and Relay Data are handled exclusively as NDU(s)

- IPN services
  - Stream accounting is provided for Received Telemetry frames (not for user)
    - Continuous sequences of Frame of matching quality are account for as a block
      - RAF accounting is by number of frames and a duration
      - RCF accounting is by frame sequence number within a VC and the duration
  - Stream accounting is provided for Received Telemetry packets (for user)
    - Packet Services: This service would select packets by their APID for inclusion in a derived NDU
      - Metadata would be created for each NDU
  - NDU Services
    - CFDP Service is the only NDU service provided by IPN:
      - » This service transforms the CFDP packets into the NDUs
      - » Transaction received metadata is used for each individual transaction NDU received
        - \* Name, size, time of creation, other attributes (e.g. destination, priority (time to live), QOS)
      - » NDU will be accounted for an E-E basis
        - \* Accounting begins with inventory unit created in the originating Asset

# SSR Buffer Data Handling Services

EEIS Relay Requirements

4/19/2002

NASA Mars Program

- Instrument or Relay data are processed using the same C&DH toolset
  - Unformatted stream data are transformed into units for data management
    - upon completion of “pass” the SSR contents are identified as an NDU
      - non-instrument specific processing could add/extract metadata
        - » time created, instrument, activity, etc
      - instrument/S/C specific processing could transform the data as required
        - » contents would be processed by on-board instrument/ S/C specific processing tools
  - Buffer contains CCSDS Packets
    - Packets could be separated for special processing by APID
      - build telemetry NDUs countaining selected APIDs for real time or off line delivery
    - CFDP Packets/PDUs could be used to translate pass data into multiple NDU
      - each file will carry its own metadata:
        - » File name, size, time of creation, other attribute
        - » routing information (e.g. destination, priority (time to live), QOS)

# Data Accountability

*EEIS Relay Requirements**4/19/2002**NASA Mars Program*

- Data Units produced on-board are accounted for from Conception to final Archival or delivery by Mars Network OPS (for projects using relay services)
  - Science teams project activity volumes by instrument
  - Instrument teams manage selected data for on-board processing
  - MOS Data management monitors all data activities
    - accounts for data generated by each source (included in S/C inventory units)
    - accounts for sub-products created by on-board processes (and relation to original NDUs)
    - accounts for all level 0 packet streams and NDUs received on earth (including completeness)
    - accounts for NDUs delivered to ground processing facilities
    - accounts for NDUs received from PIs for PDS Archival (relationship to original level 0/1 NDUs)
  - Instrument teams manage the data delivered to them
    - accept responsibility for processing data and delivery to PDS
    - PDS deliveries shall identify relation to original data delivered to Instrument teams
  - Mars Network OPS team provide data handling and delivery for Landed Assets
  - Deep Space Network OPS accounts for telemetry data captured and delivered
    - uses SOEs for projected volumes
    - uses volume from frames received for comparisons with Packet and NDUs to estimate performance for transformation of frames to Packets and NDUs

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# CONCLUSION

